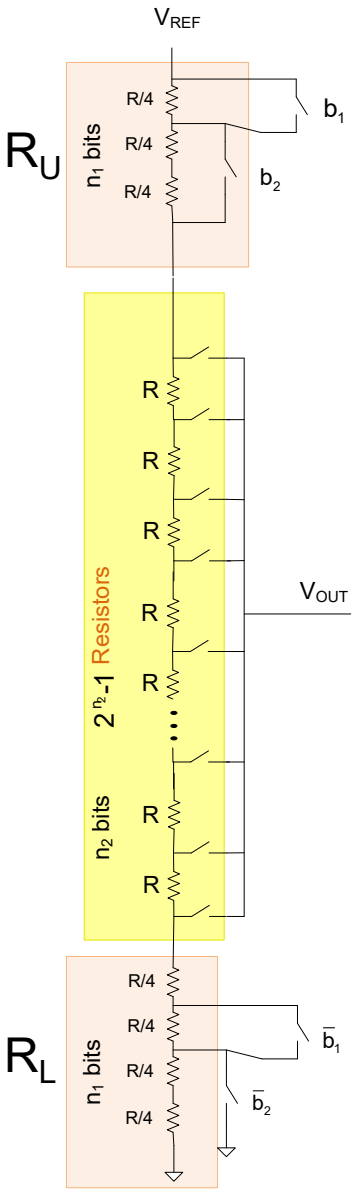
EE 435

Lecture 35

Current Steering DACs

Basic R-String DAC

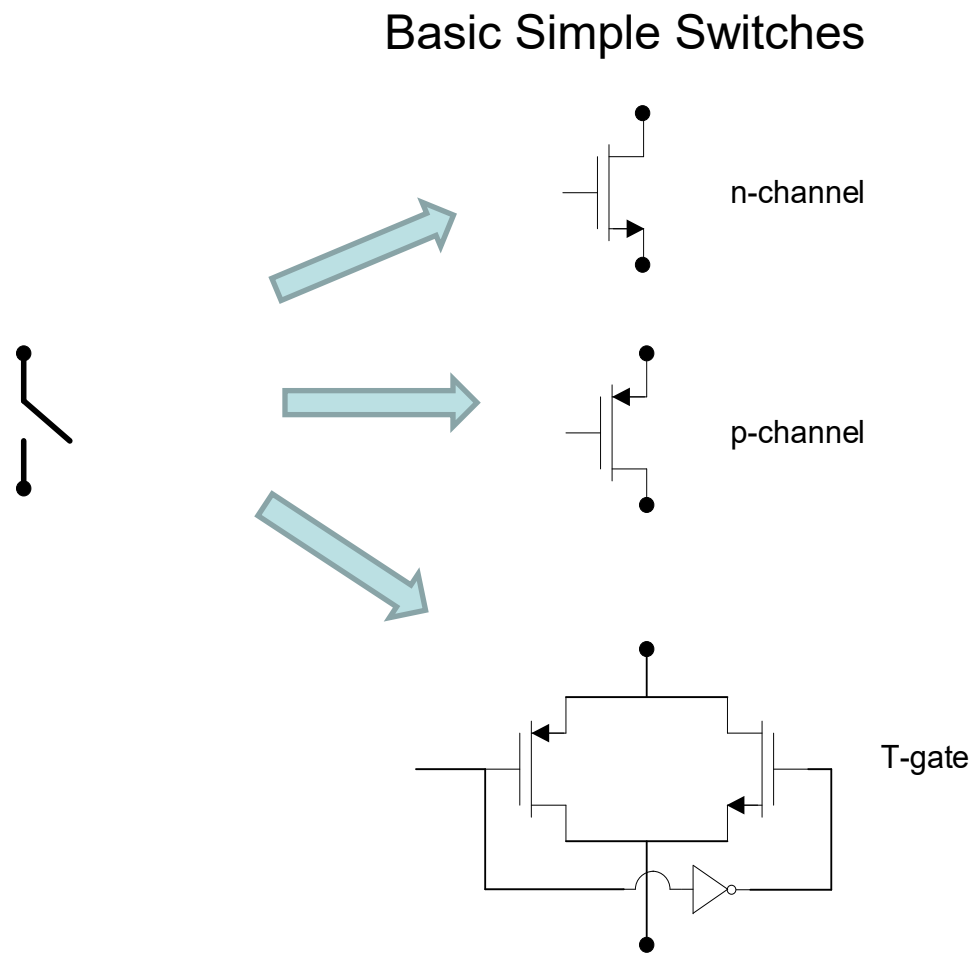


For all b_1 and b_2, $R_U+R_L=R$

- Another Segmented DAC structure
- Can be viewed as a “dither” DAC
- Often n_1 is much smaller than n_2
- Dither can be used in other applications as well

Switches used extensively in data converters !

Switch Implementation Issues



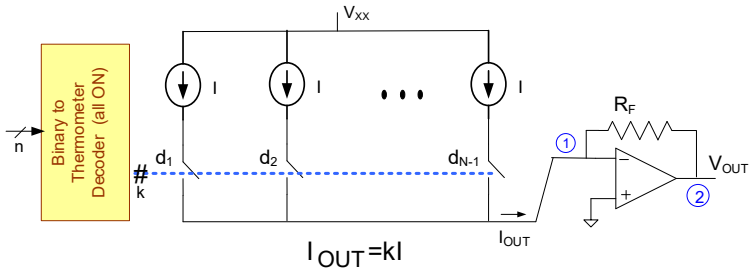
Review from Last Lecture

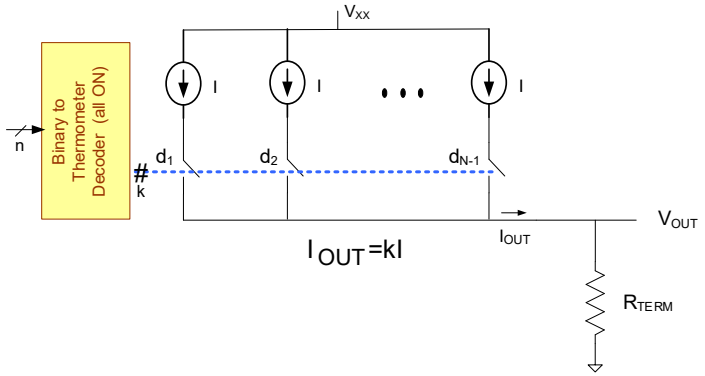
Current Steering DACs

Current will be “steered” to a resistive load (on chip)

Output could be a current (user supplies load)

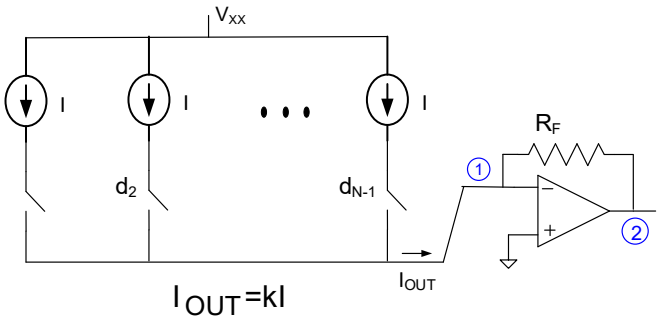
Basic Concept of Current Steering DACs

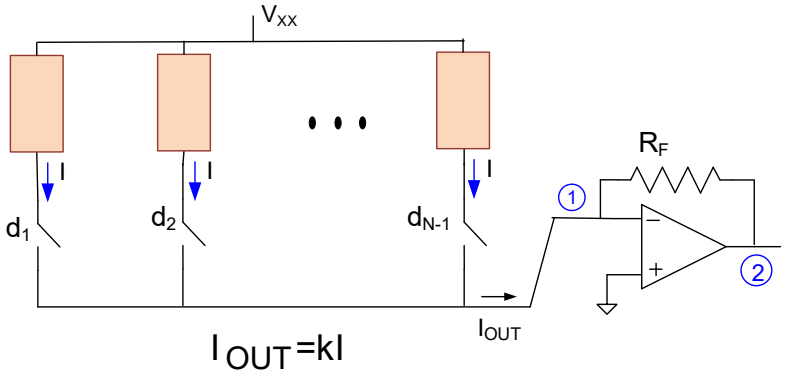




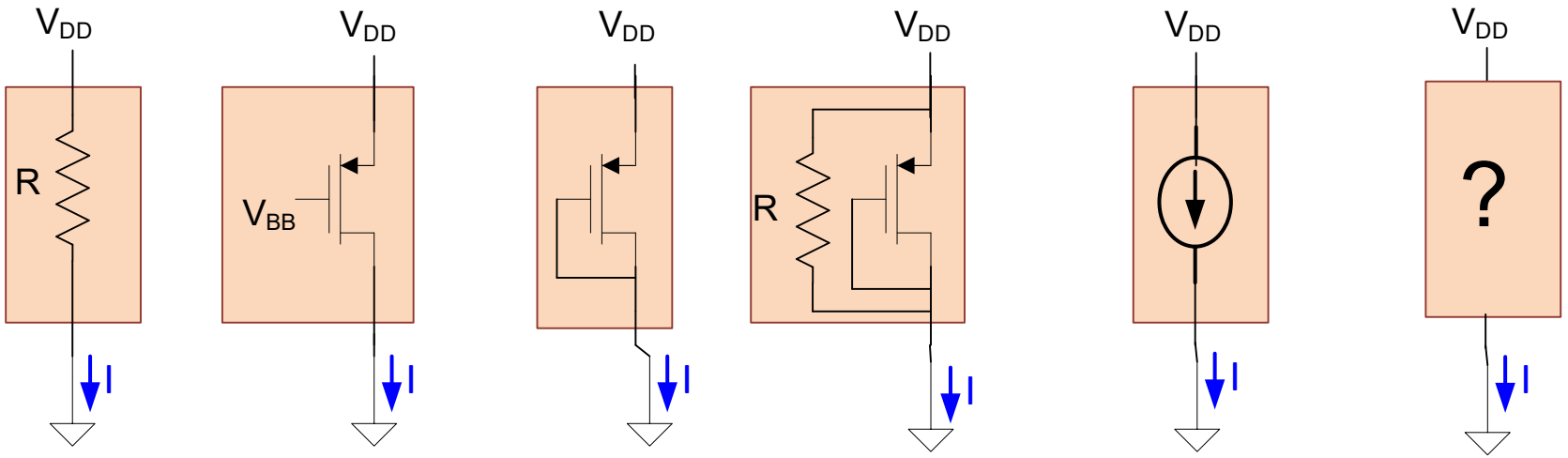
Review from Last Lecture

Current Steering DACs



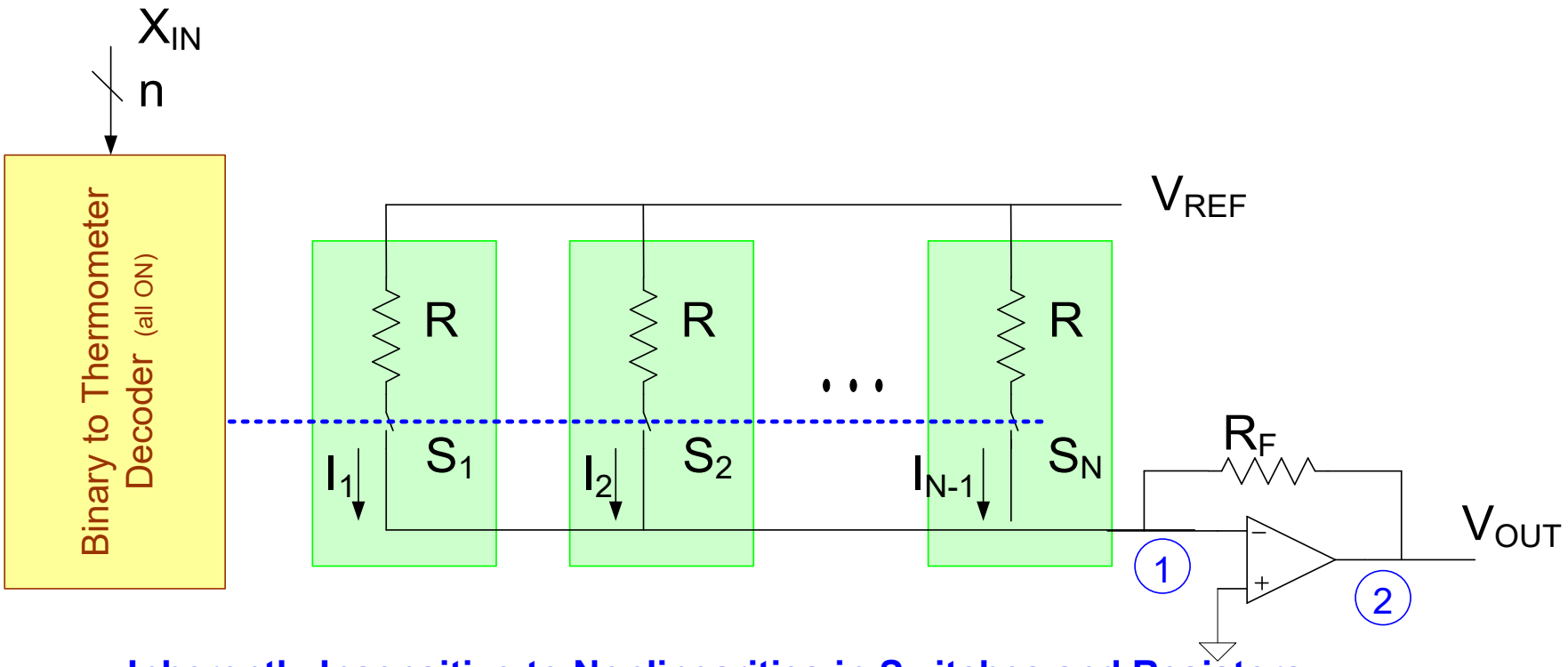


What is important is the current generated, not whether it comes from a “current source”



Many potential current generator blocks, just require that all be ideally identical

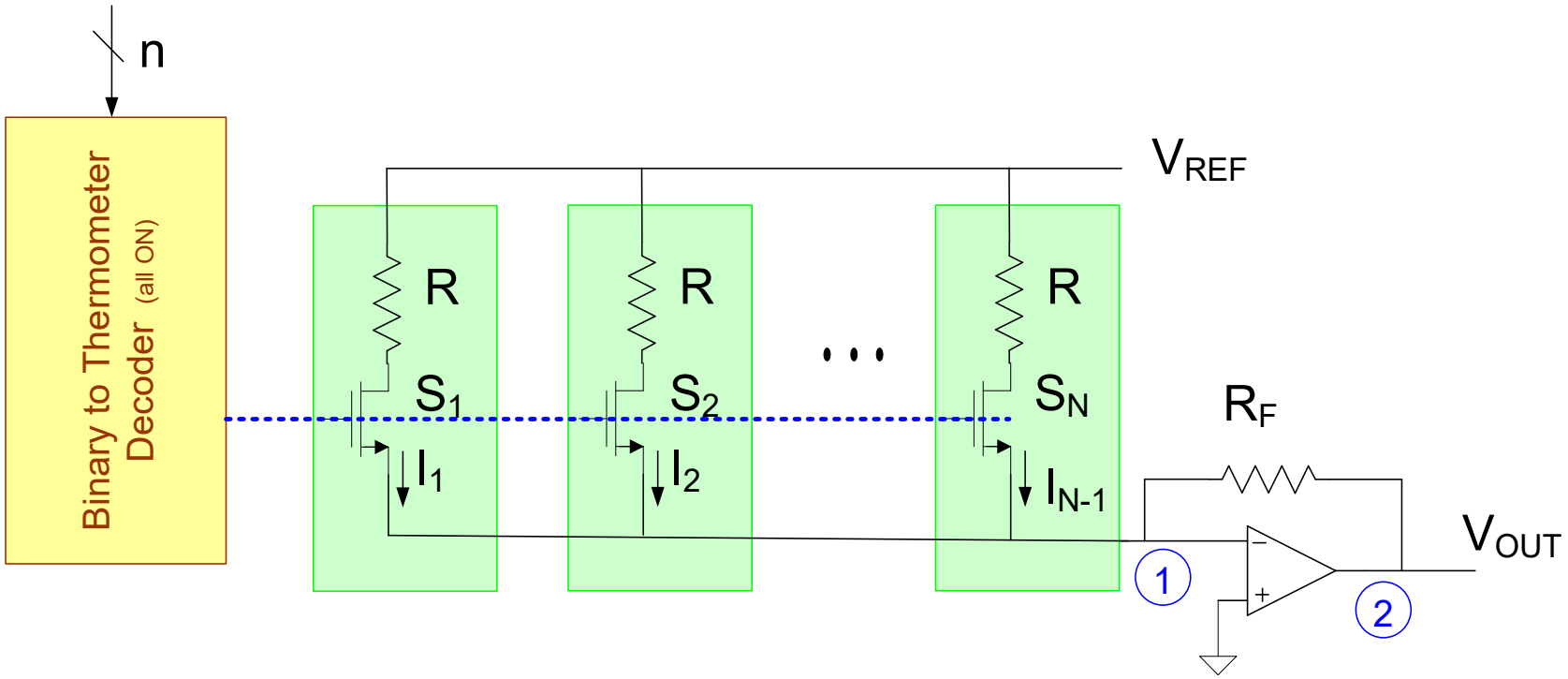
Current Steering DACs



Inherently Insensitive to Nonlinearities in Switches and Resistors
Smaller ON resistance and less phase-shift from clock edges

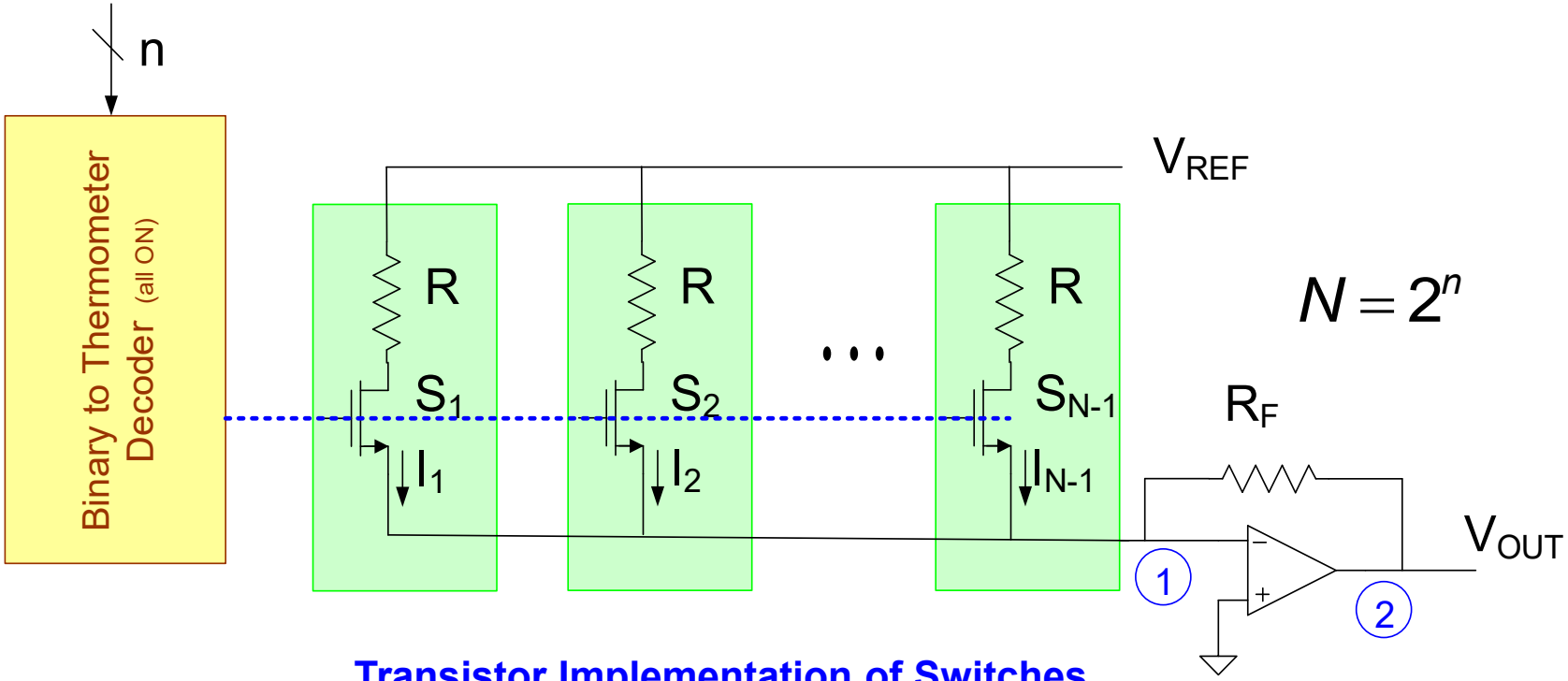
- Termed “bottom plate switching”
- Thermometer coded

Current Steering DACs



Transistor Implementation of Switches

Current Steering DACs



Transistor Implementation of Switches

How should the op amp be compensated?

Assume k switches are on 0<k<N-1

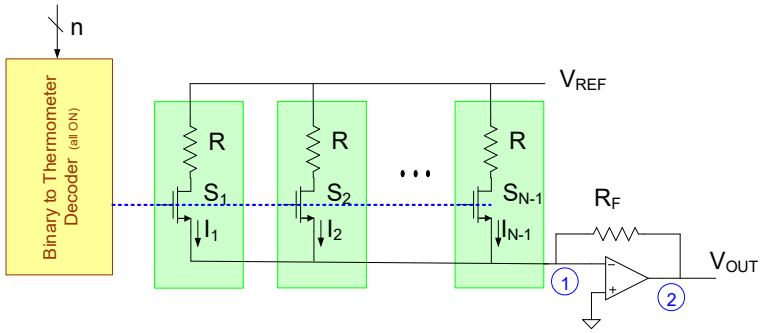
$$\beta = \frac{\frac{R_{CELL}}{k}}{\frac{R_{CELL}}{k}+R_F} = \frac{R_{CELL}}{R_{CELL}+kR_F}$$

If $V_{OUTFS} = V_{REF}$ $R_{CELL} = NR_F$

$$0.5 < \beta \leq 1$$

How should the op amp be compensated?

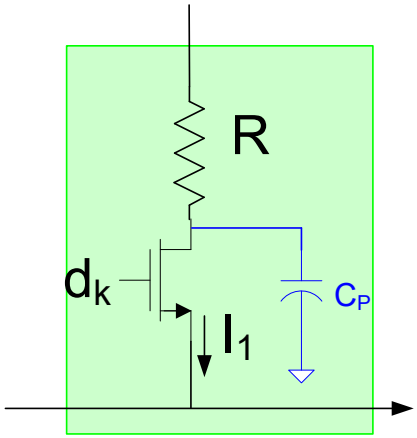
$$\beta = \frac{\frac{R_{CELL}}{k}}{\frac{R_{CELL}}{k} + R_F} = \frac{R_{CELL}}{R_{CELL} + kR_F}$$

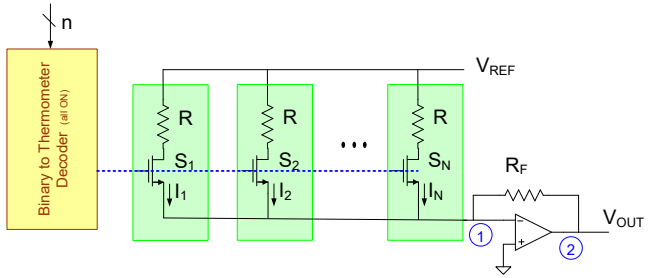


$V_{OUTFS} = V_{REF}$

$0.5 < \beta \leq 1$

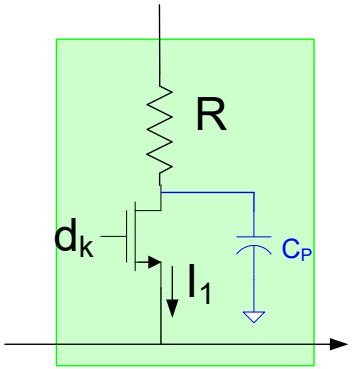
Current Steering DACs

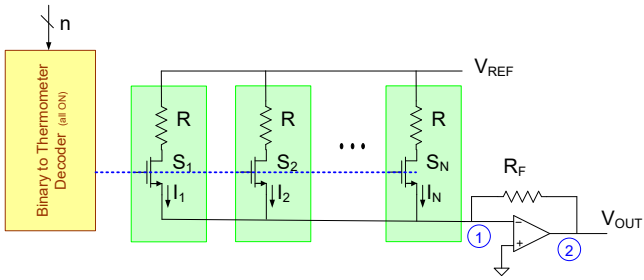


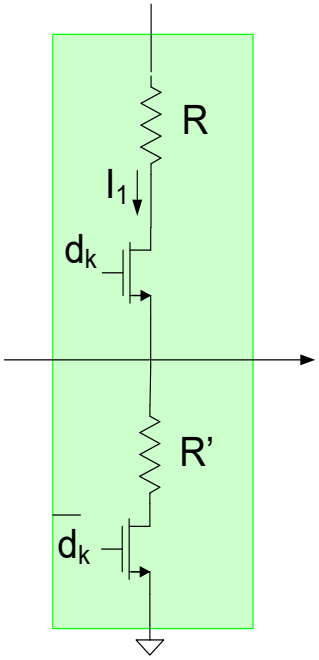


	Problem?
Switch impedance	No
Code-dependent phase margin	Yes
Single-ended output	Yes
C_P	Yes
Binary to Thermometer Decoder	Yes
Op Amp Bandwidth	Yes

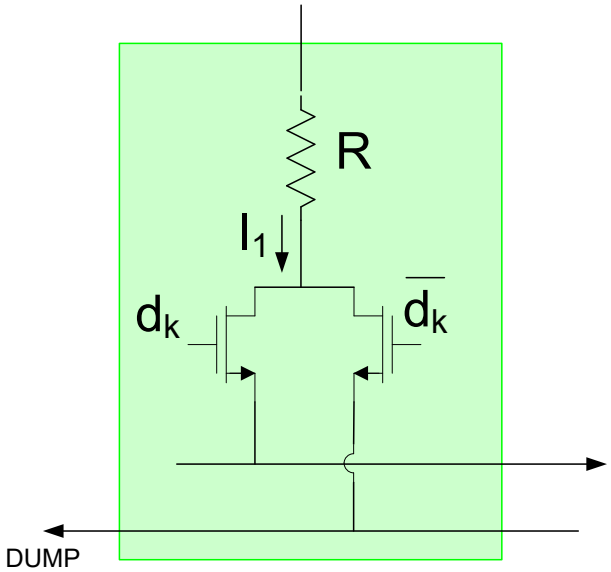
Current Steering DACs



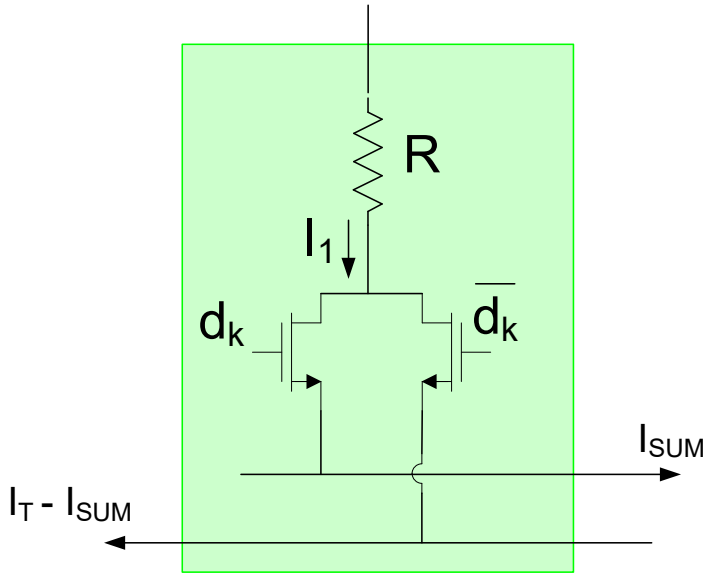




β Compensation



C_P Compensation
(steer rather than switch)

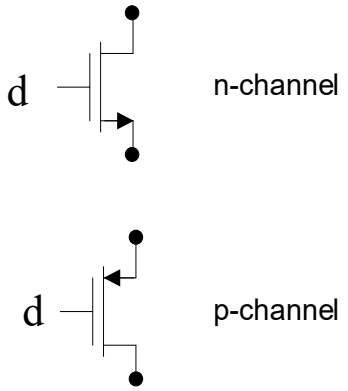


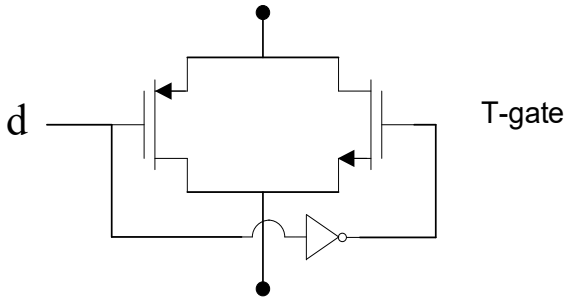
Differential Output

Switches used extensively in data converters !

Switch Implementation Issues

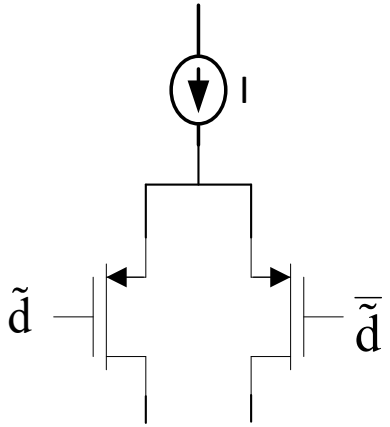
Basic Simple Switches





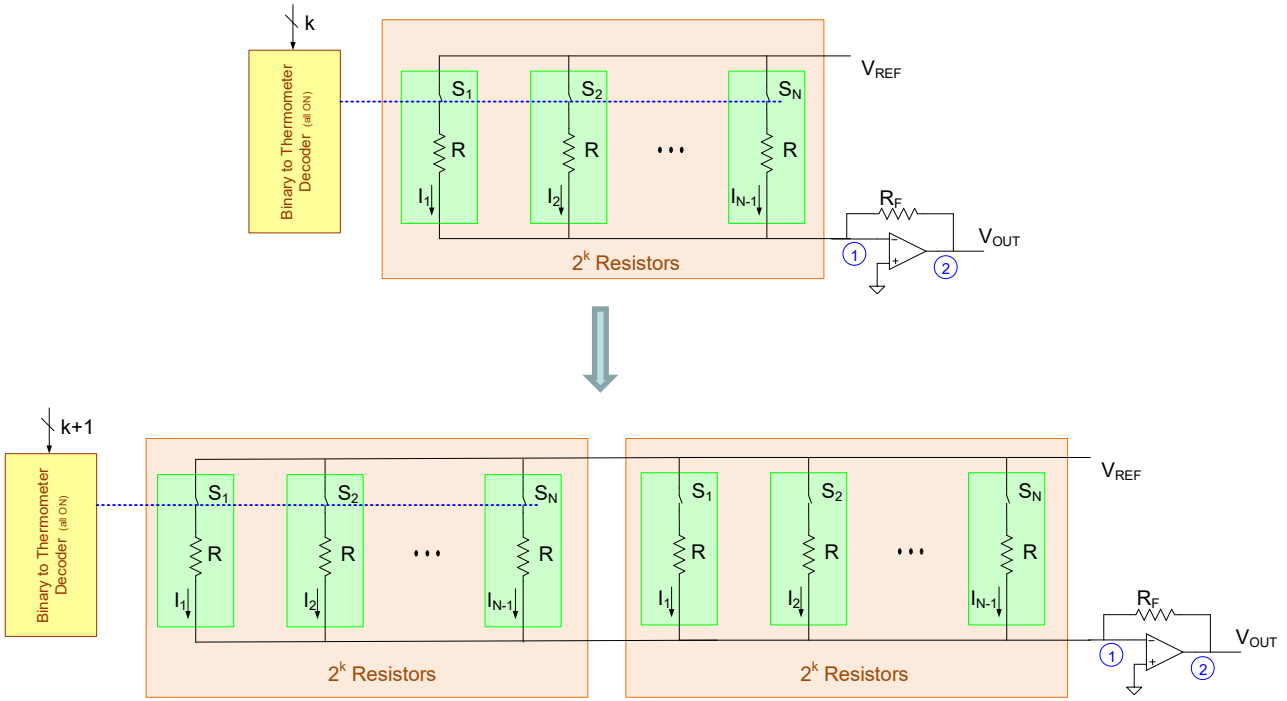
Transistors switch between deep cutoff and deep triode

Basic Current Steering



- Transistors avoid triode region and deep cutoff
- Reduced Boolean Input Levels

Current Steering DACs



approximately $\sigma = \frac{A_{PEL}}{\sqrt{A}}$

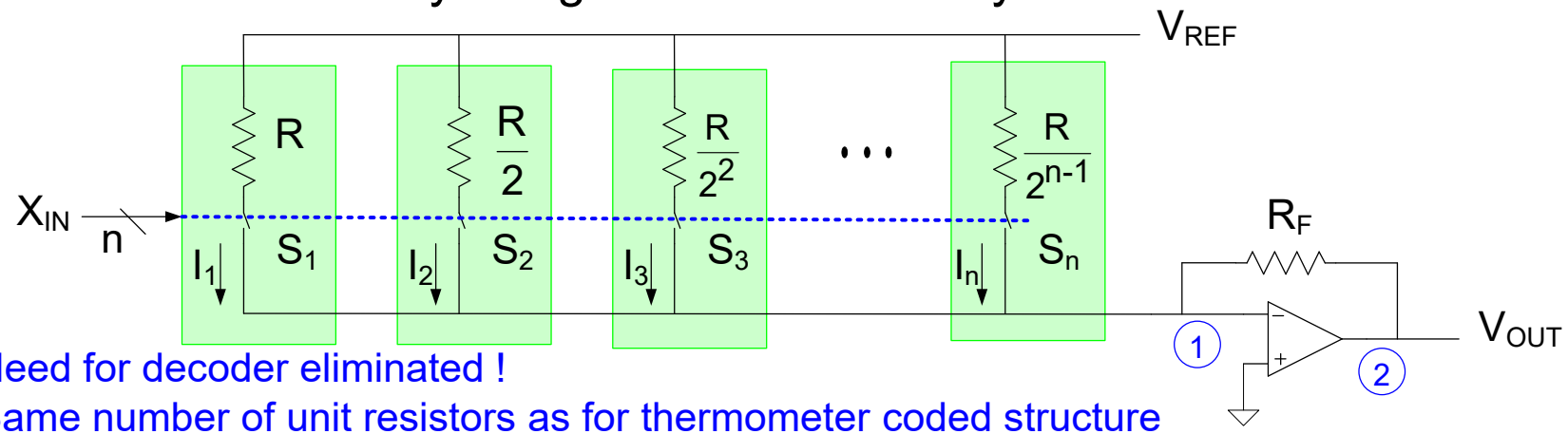
Consider a k-bit structure that has an acceptable (and desired) yield of Y

Can a k+1 bit structure be easily implemented by simply making 2 copies of the resistor array and adding one bit to the decoder?

The one-afternoon design ?

Current Steering DACs

Binary-Weighted Resistor Arrays



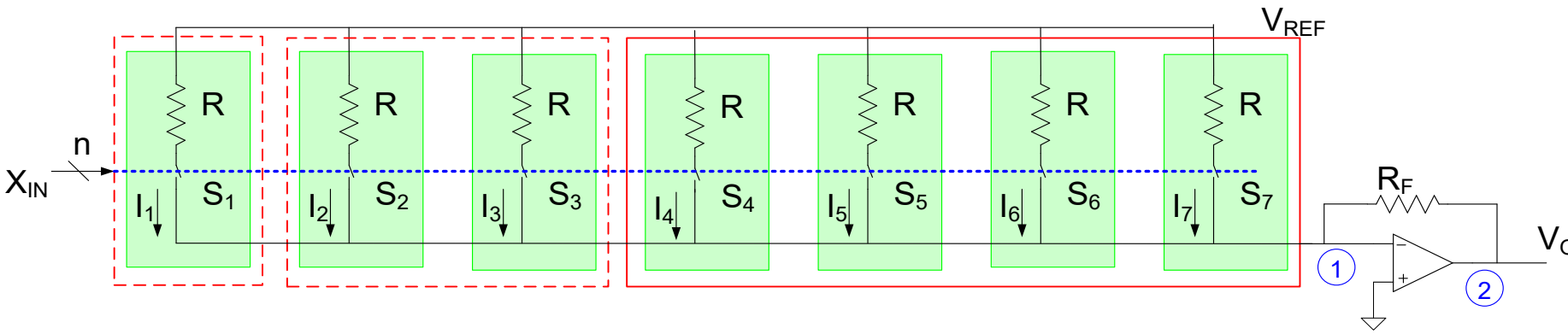
- Need for decoder eliminated !
- Same number of unit resistors as for thermometer coded structure
- DNL may be a major problem
- INL performance about same as thermometer coded if same unit resistors used
- Sizing and layout of switches is critical
- Unary resistor arrays usually used with common-centroid layout(at least for MSB)
- Ratio matching strongly dependent upon area (if common-centroid used to eliminate gradients)
- INL is a random variable with variance approximately proportional to $\sigma = \frac{A_{PEL}}{\sqrt{A}}$
- Area gets large for good yield with large n

Observe thermometer coding and binary weighted both offer some major advantages and some major limitations

- Thermometer coding (particularly of MSBs) reduces DNL
- Binary coding reduces/eliminates binary:thermometer decoder

Can benefits of thermometer coded and binary weighted structures be obtained?

Current Steering DACs



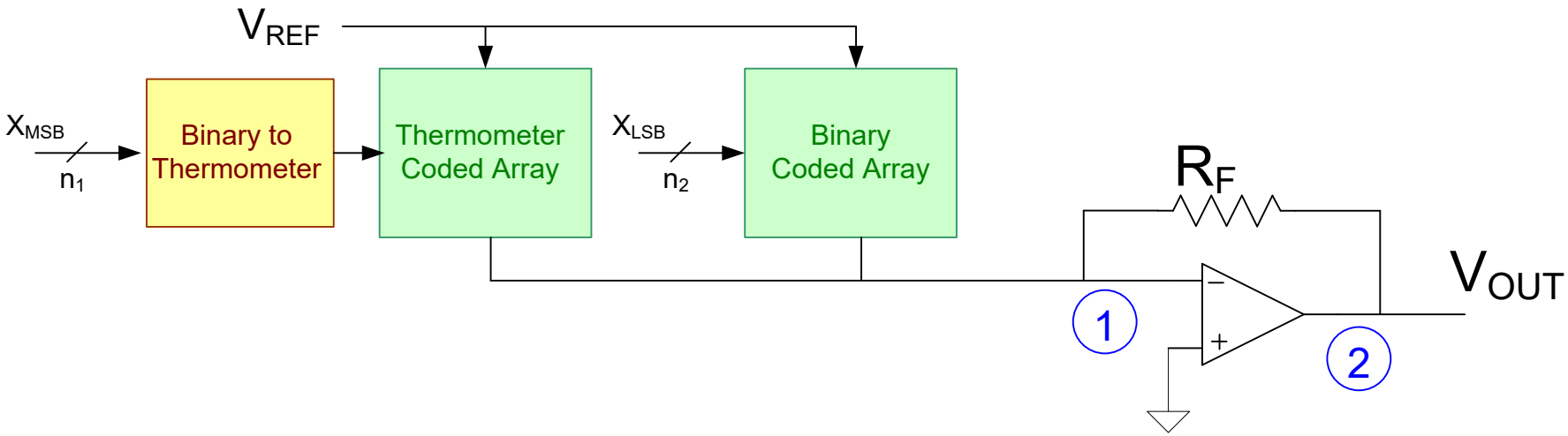
Binary-Weighted Resistor Arrays

As stated earlier, bundled unary cells are almost always used

Actual layout of resistors is very important

Common centroid layout is desired but may not be practical with a large number of elements

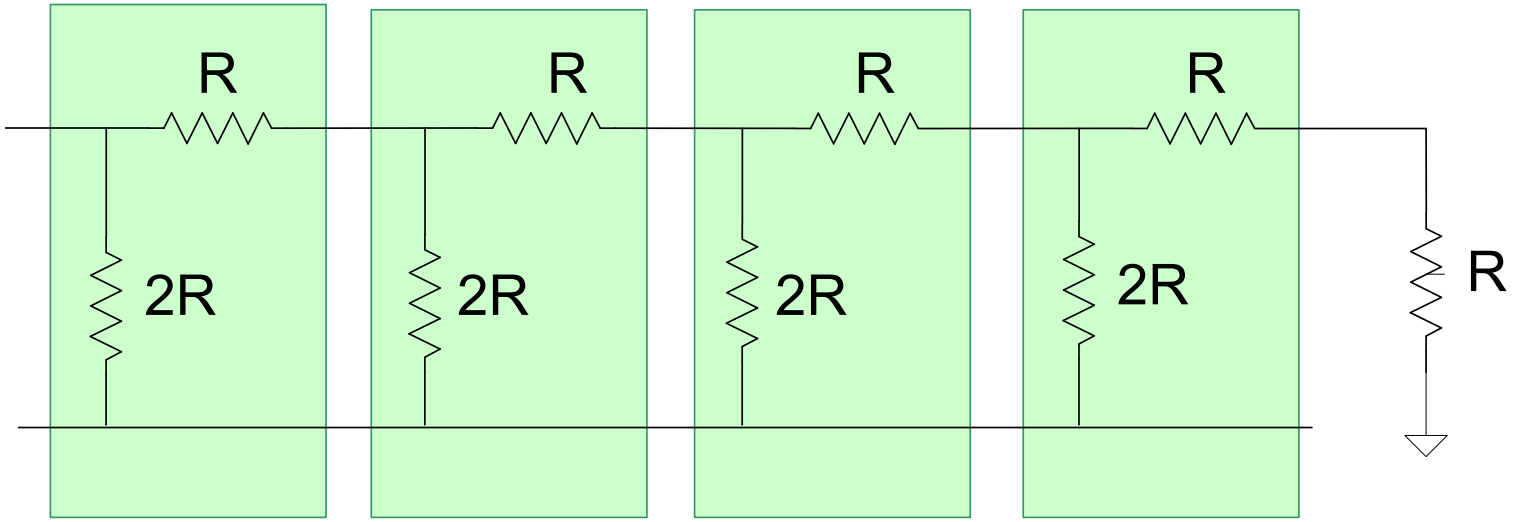
Current Steering DACs



Segmented Resistor Arrays

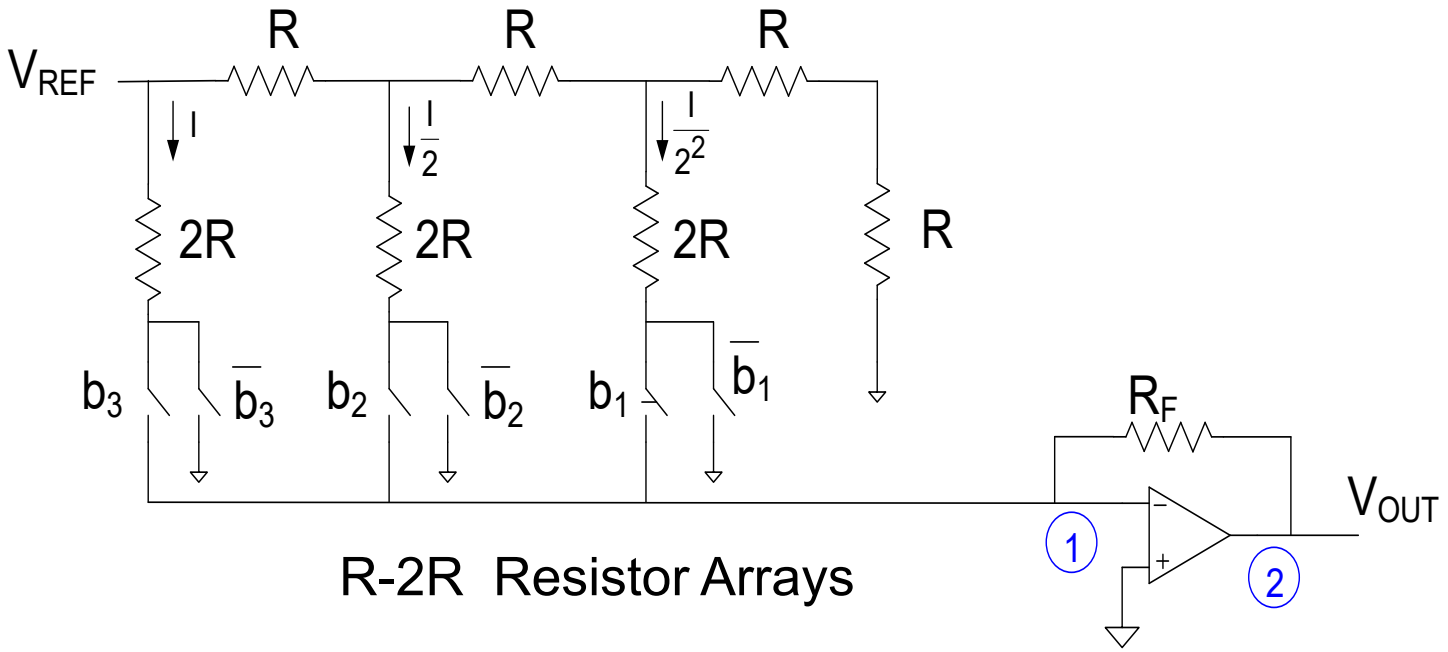
- Combines two types of architectures
- Inherits advantages of both thermometer and binary approach
- Minimizes limitations of both thermometer and binary approach

R-2R Resistor Arrays



- 4 bit-slices shown
- Can be extended to arbitrary number of bit slices
- Conceptually, area goes up linearly with number of bit slices

Current Steering DACs



R-2R Resistor Arrays

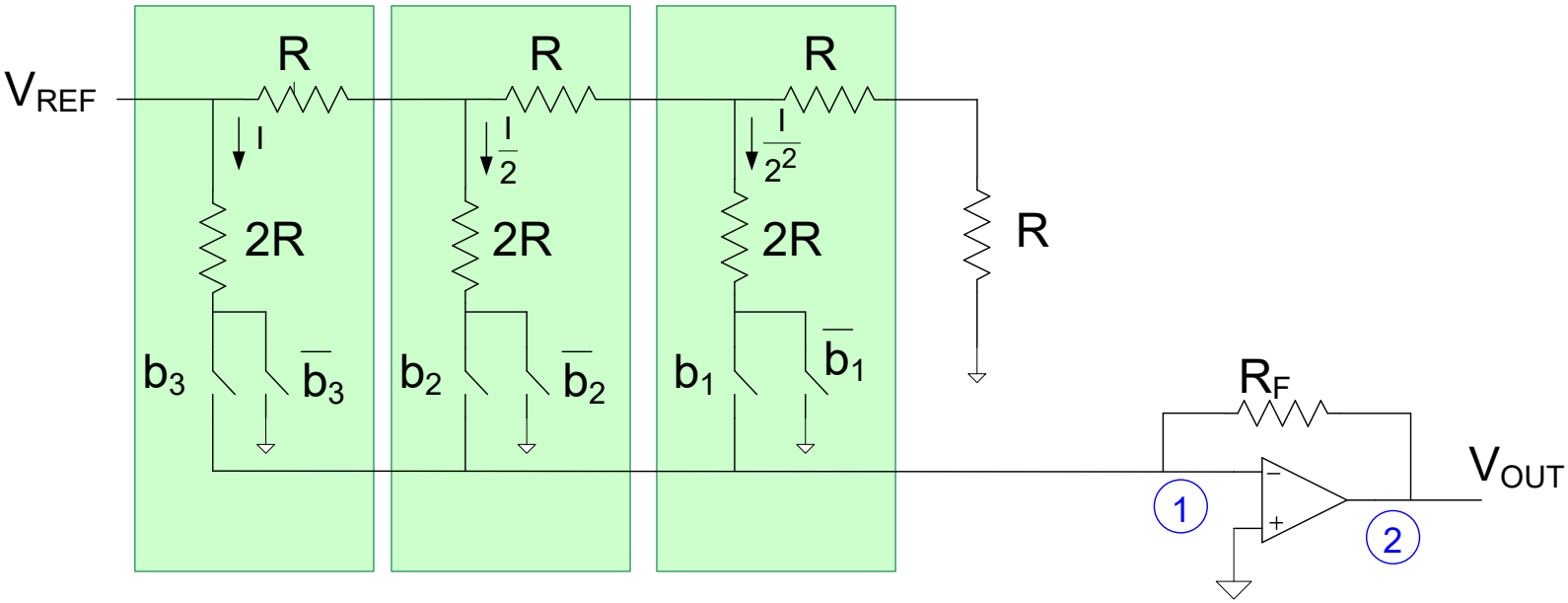
Eliminates need for decoder

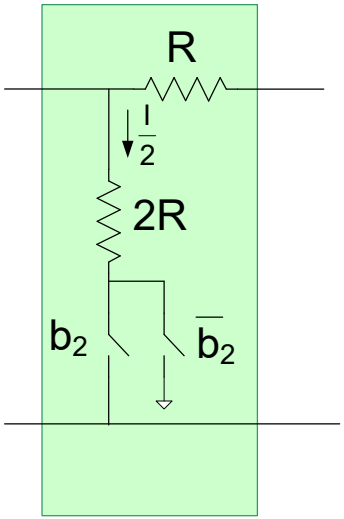
Node voltages ideally stay constant for any input code

Highly sensitive to nonlinearities in switches

How should switches be sized?

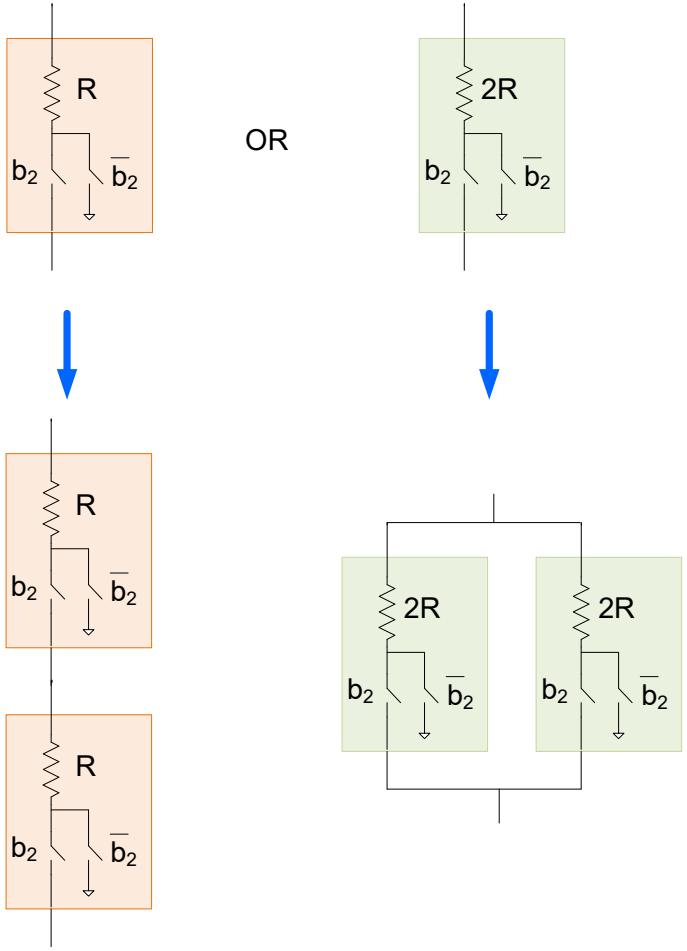
Current Steering DACs





R-2R Resistor Arrays

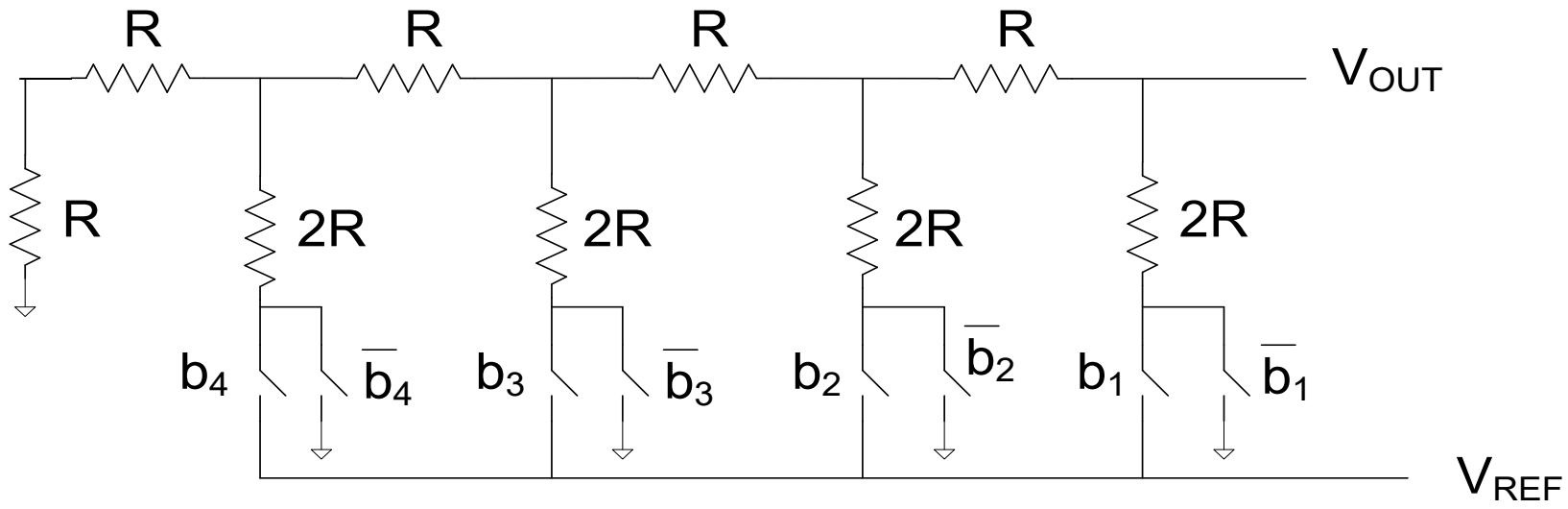
R-2R Implementation



- Unit cell widely used
- Switch included in cell even if not switched!
- Switches always ON in series elements in R-2R array
- Code dependence of switch impedance of concern

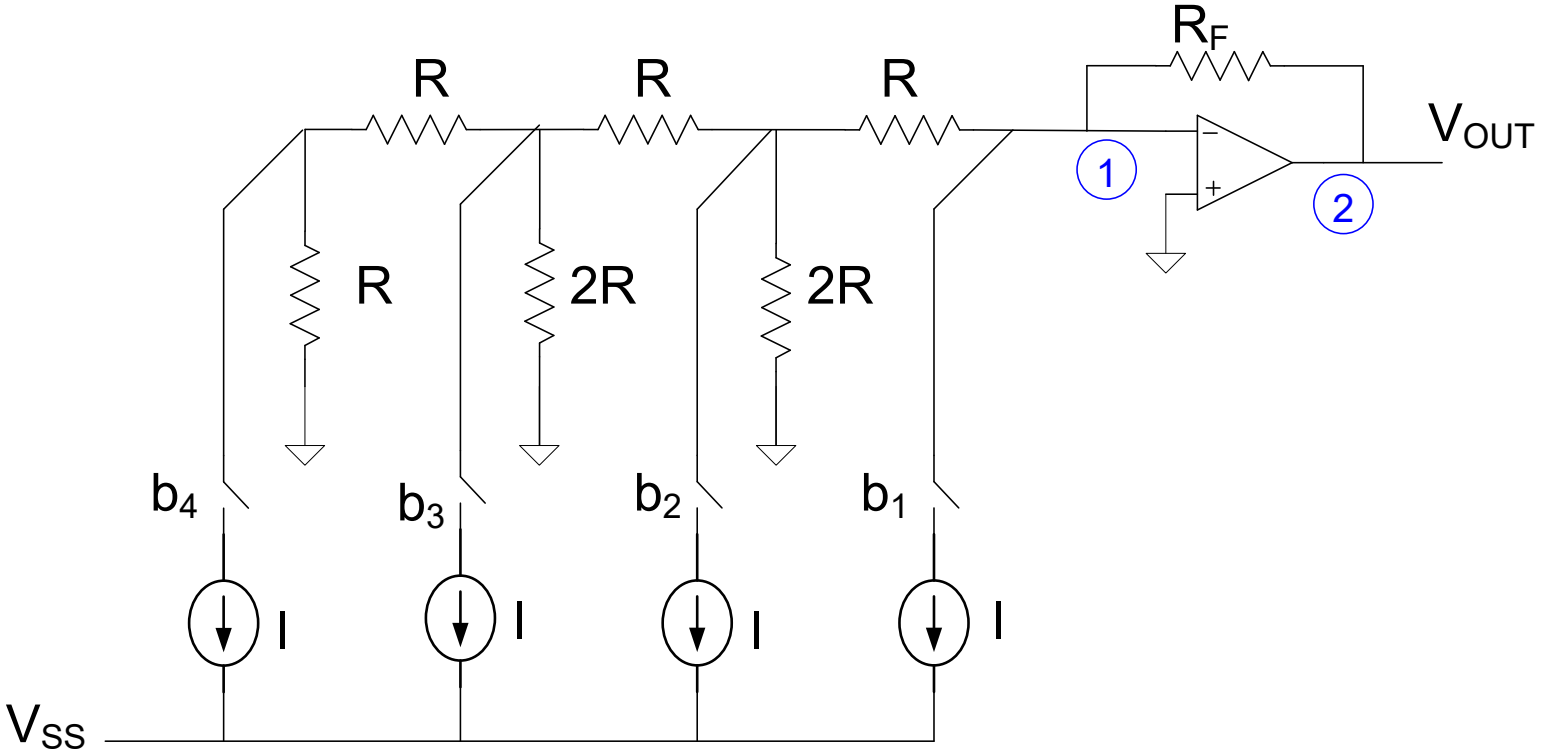
How can switch impedances be matched?

Another R-2R DAC



Node voltages change with input code

Another R-2R DAC



Switch impedance does not affect performance

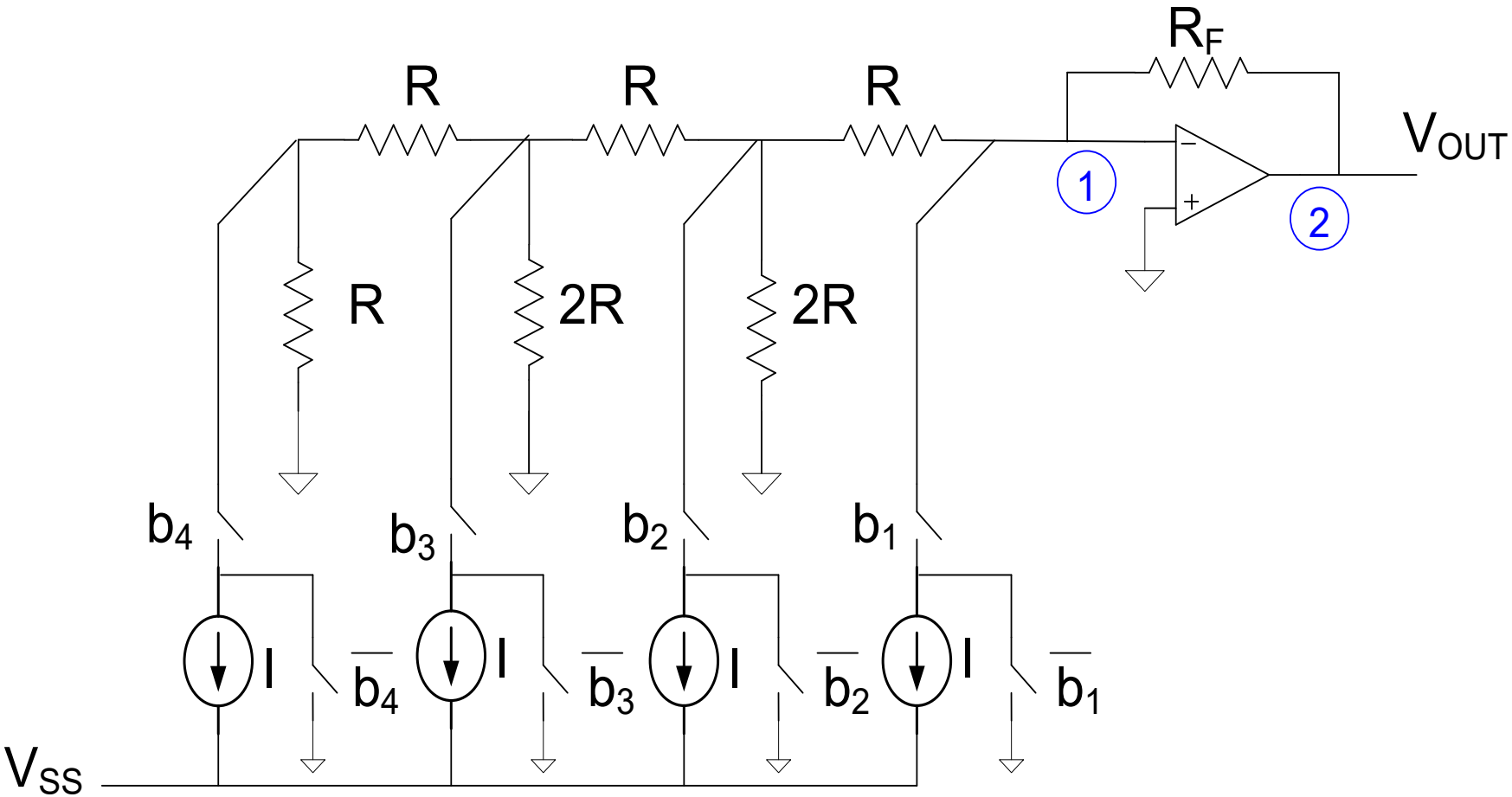
Requires matching both current sources and resistors

β is independent of Boolean code

Node voltages in R/2R block must change for any input transitions

Voltages on internal R-2R nodes must settle with input transitions

Another R-2R DAC



Clocks must be nonoverlapping

Does this offer any benefits over previous approach ?

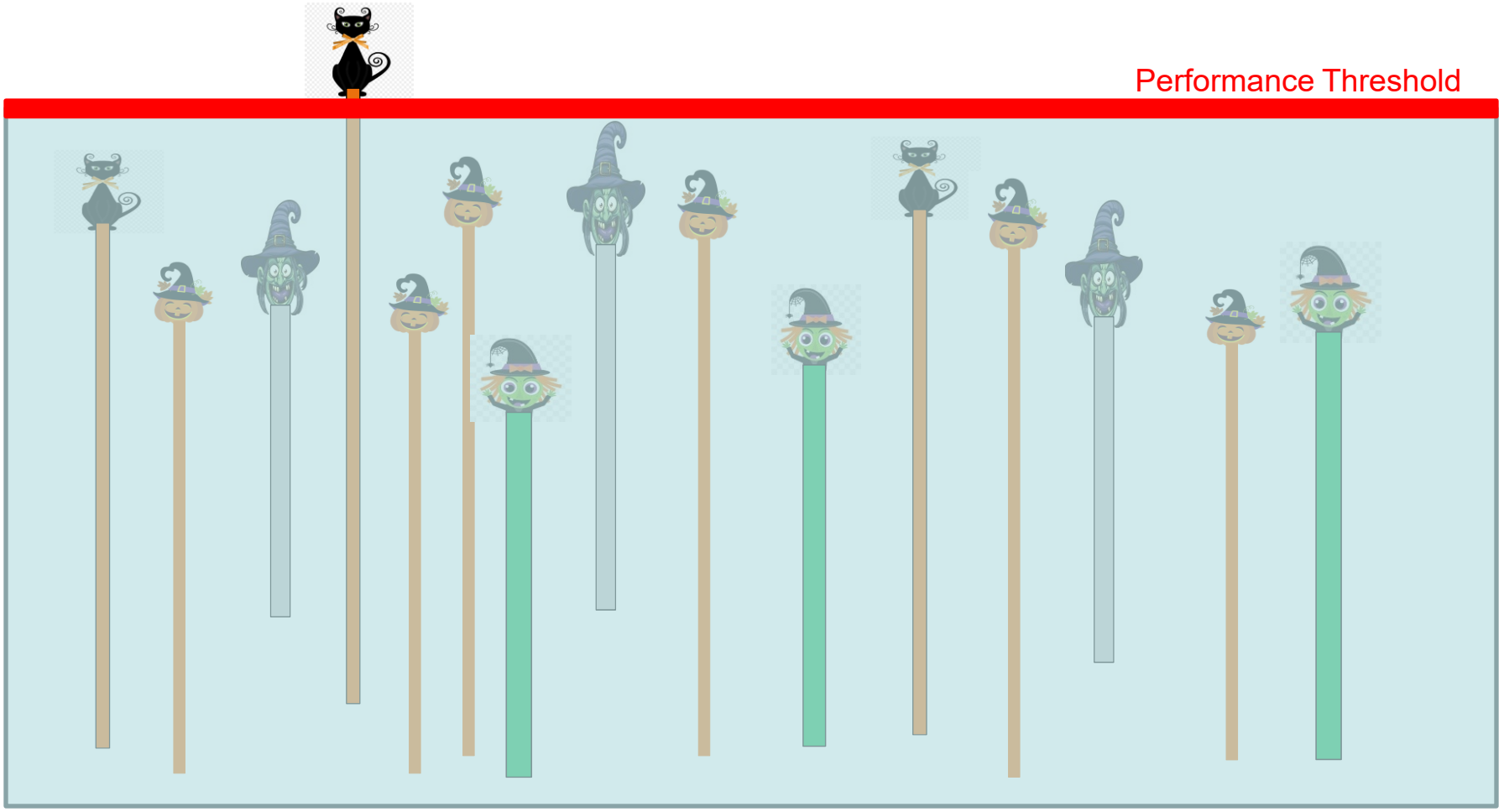
Offers some compensation for capacitances on current sources

Are there other terminations for the current sources? e.g. Dual R-2R?

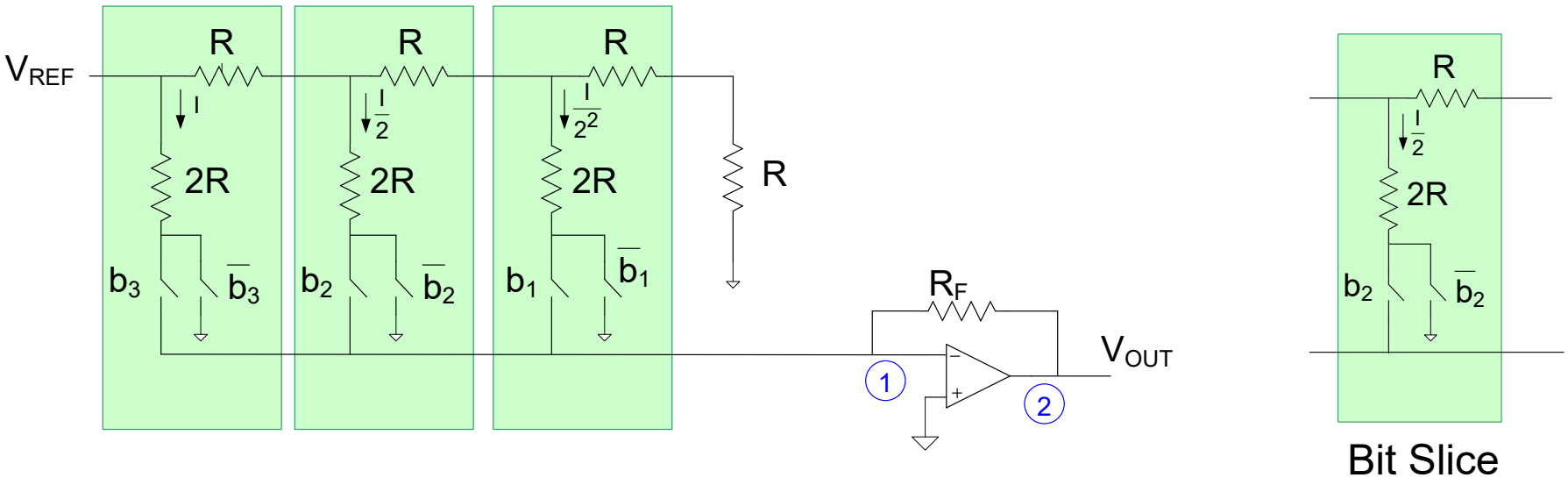
Data Converter Design Strategies

Remember:

Need to keep nonideal effects below an acceptable performance threshold



R-2R DACs



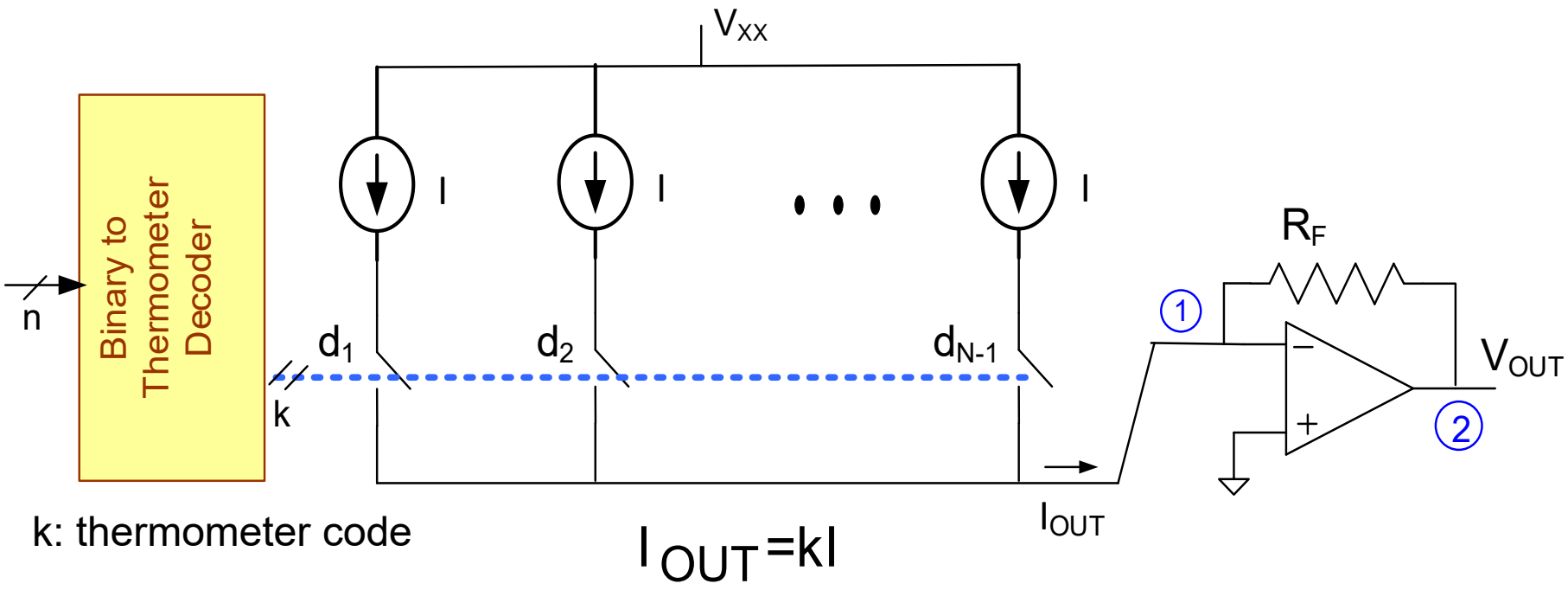
Key characteristic of R-2R Structures

- Area increases linearly with number of bits of resolution
- Binary to thermometer/bubble converter eliminated
- Simple unary cell can be used for R elements
- Common-centroid layout manageable ??

Key challenges of R-2R Structures

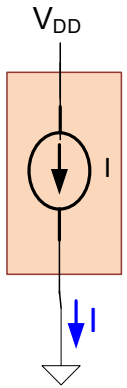
- Switches directly affect R-2R values and ratios
- Voltage on internal nodes must settle for some structures
- If unary cell used, area not optimally allocated for matching

Current Steering DAC



k: thermometer code

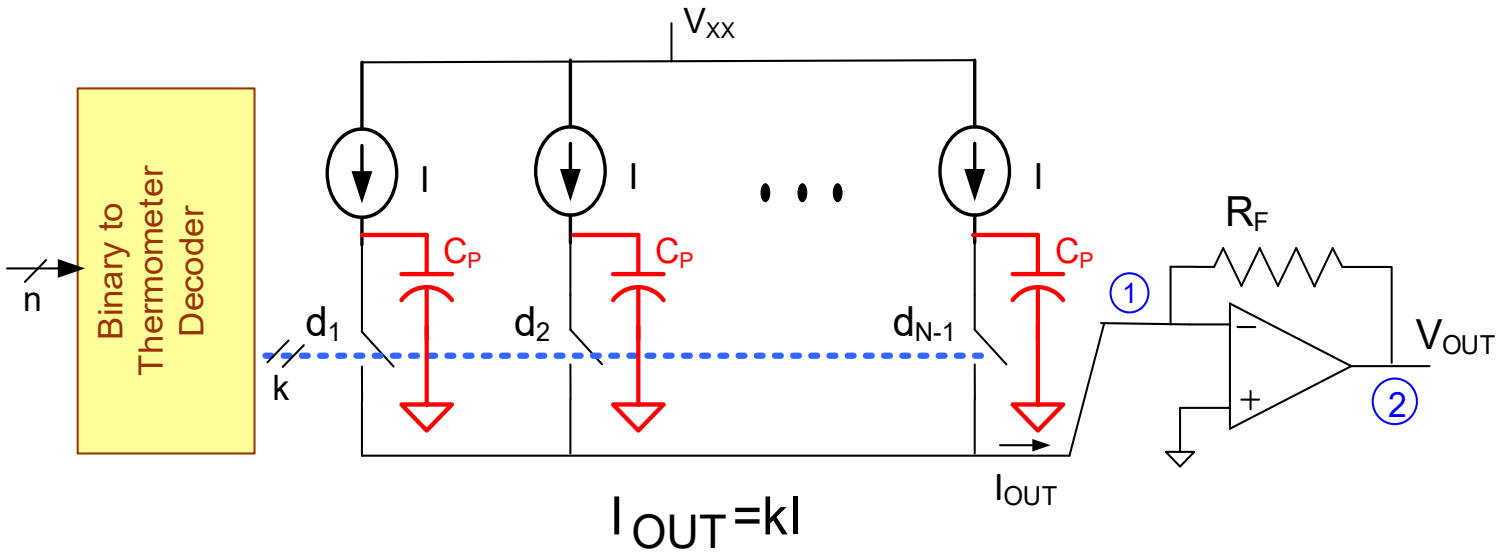
$I_{OUT}=kI$



Switch impedance of little concern if current sources ideal

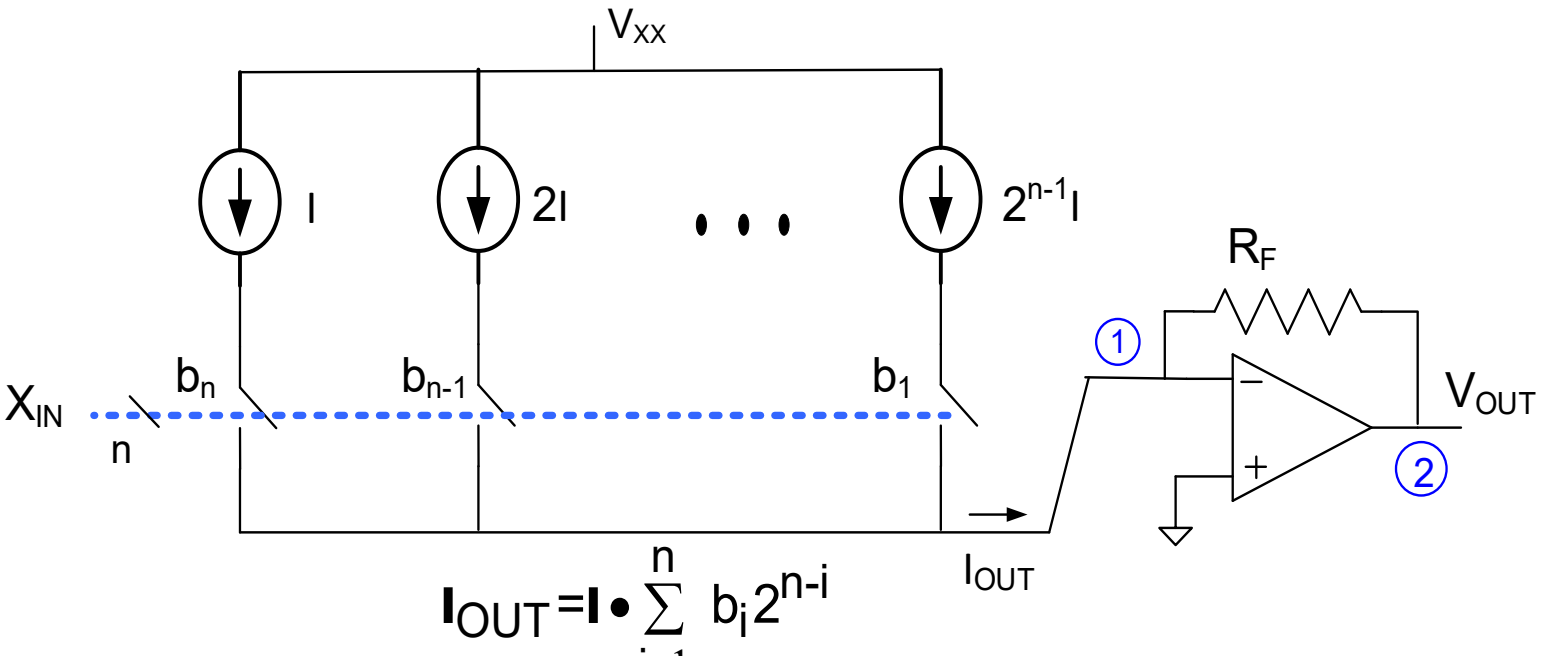
Just requires matching of current sources

Current Steering DAC



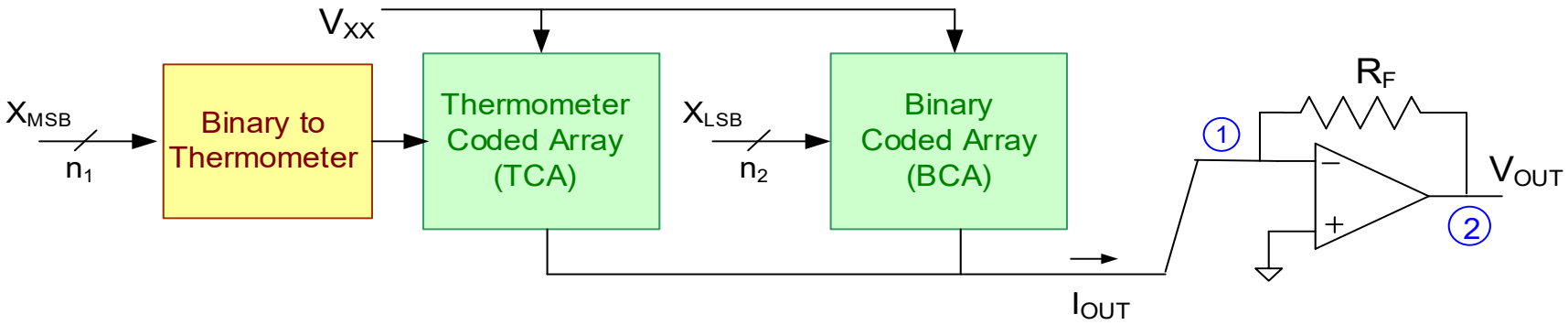
Critical parasitic capacitors in current-steering DAC

Current Steering DAC



- Binary to thermometer decoder eliminated
- Current sources bundled unary cells
- Bundles large for large n

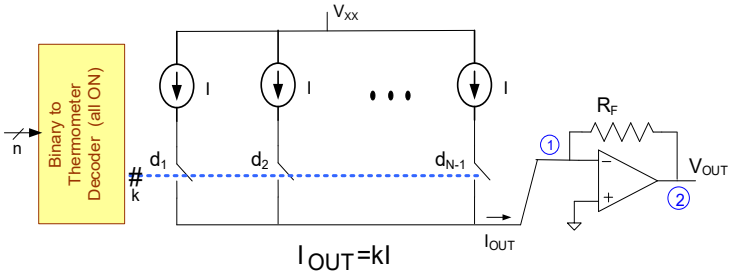
Current Steering DAC

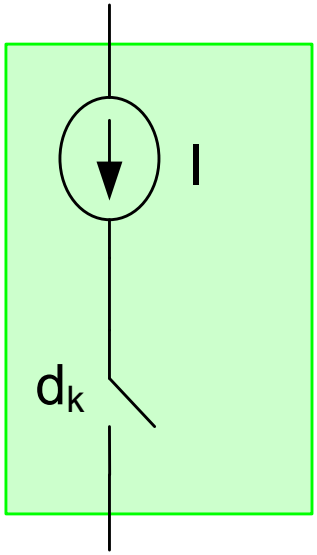


Segmented Structure

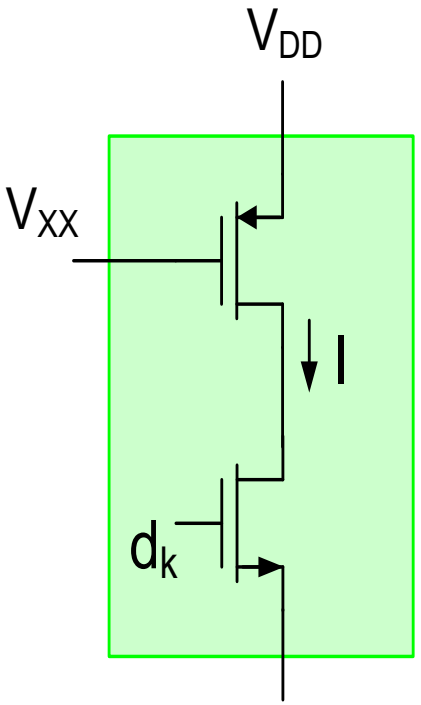
- Exploits benefits of both thermometer and binary coded structures
- Common-centroid layout likely only necessary on TCA
- Dramatic reduction in complexity of decoder possible

Current Steering DAC





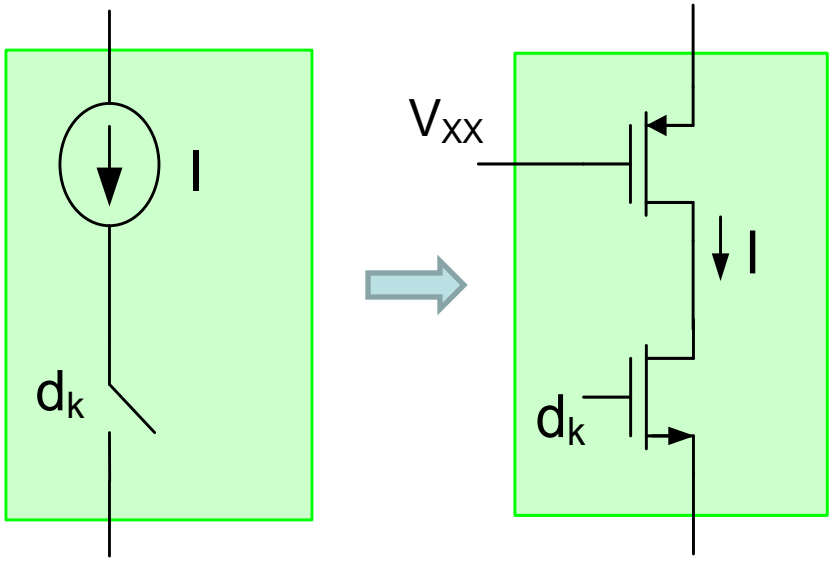
popular current source

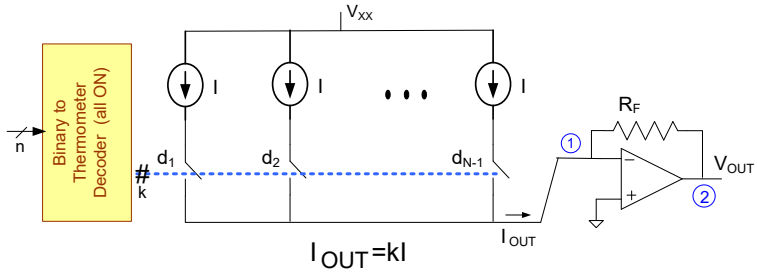


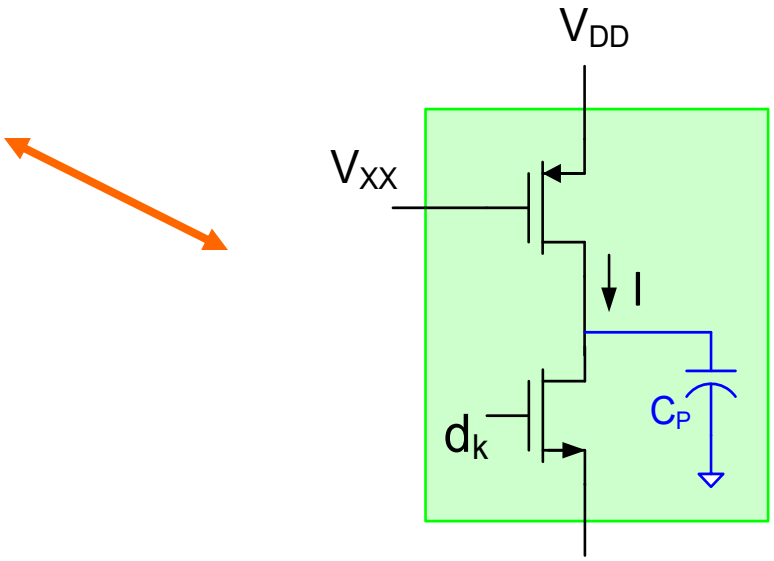
Is linearity or output impedance of current source of concern?

Not if individual slices are matched !

Current Steering DAC

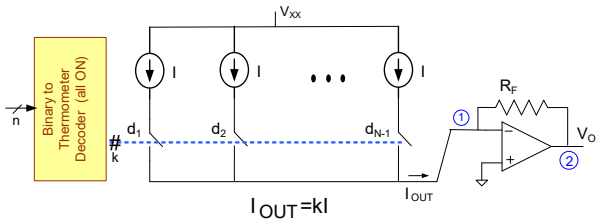


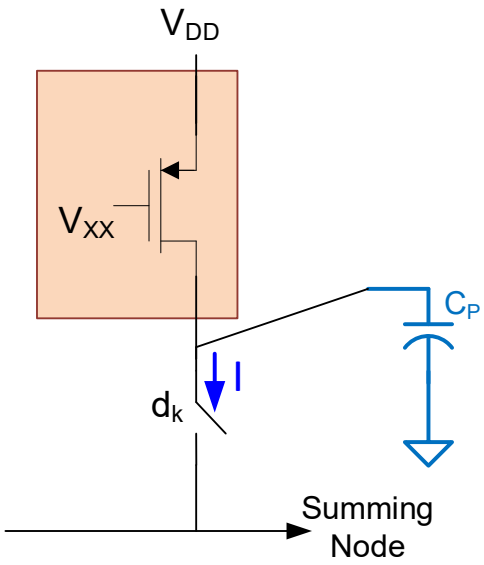


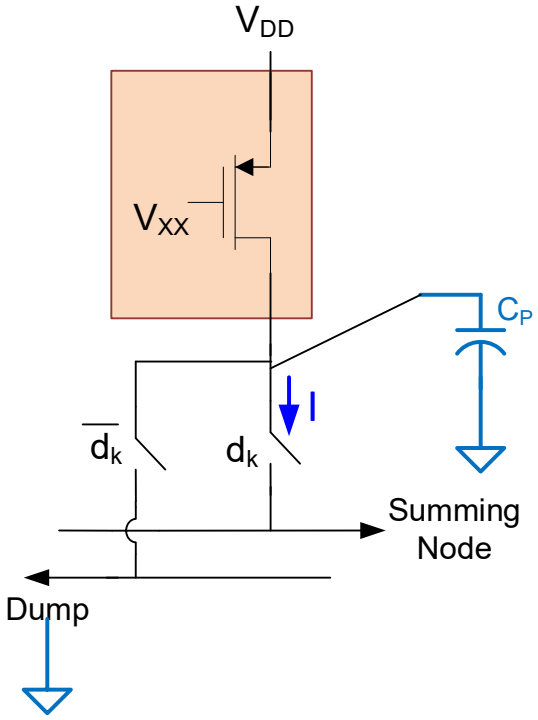


Parasitic capacitance on output of current source problematic

Current Steering DAC

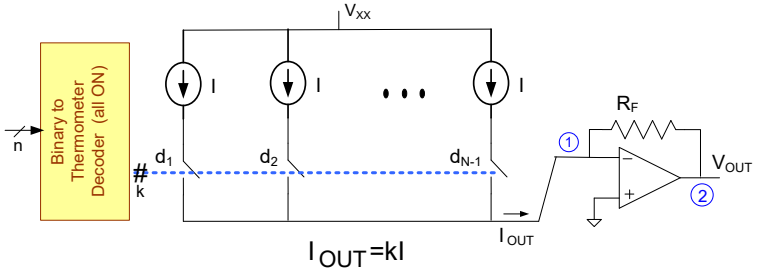


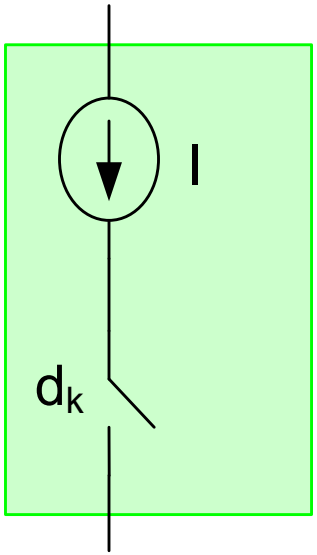




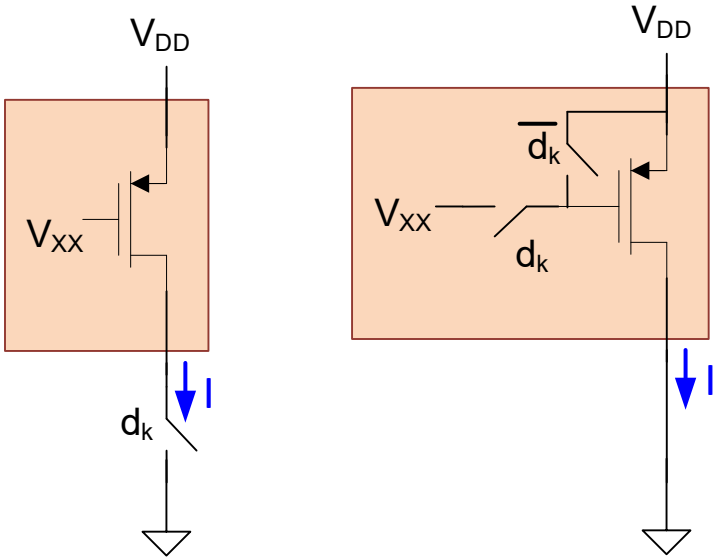
Reducing Effects of Parasitic capacitance on output of current source

Current Steering DAC





Alternative current source cells

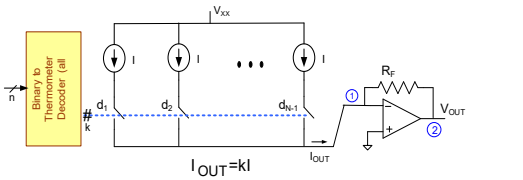


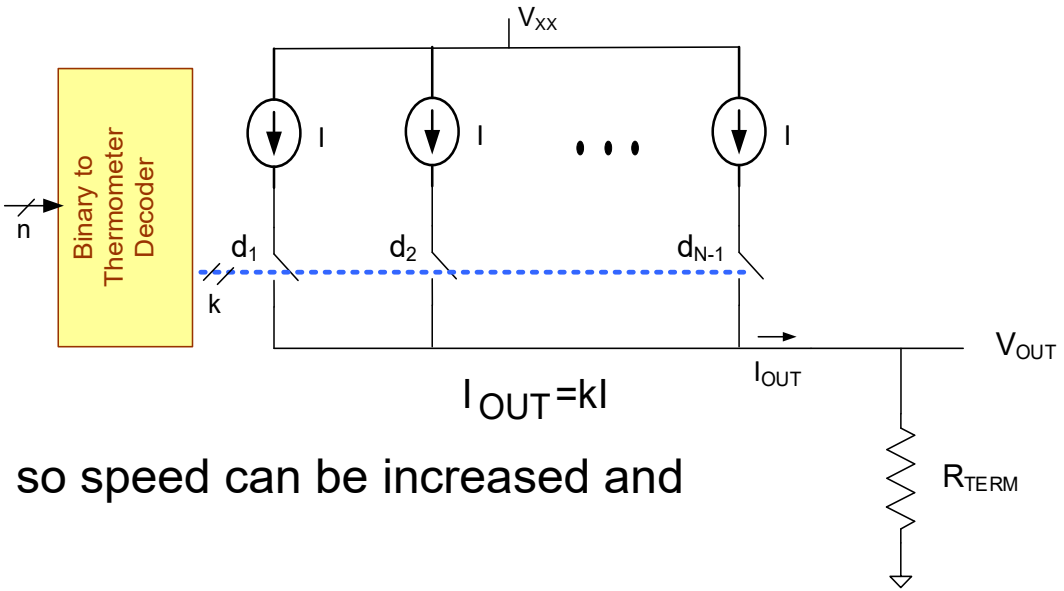
Which is better?

Effects of parasitic diffusion capacitance?

Effects of gate capacitance?

Current Steering DAC





Op Amp can be eliminated so speed can be increased and power reduced

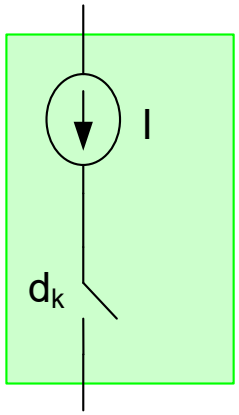
R_{TERM} often 50Ω or 100Ω

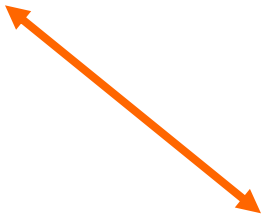
R_{TERM} can be internal or external

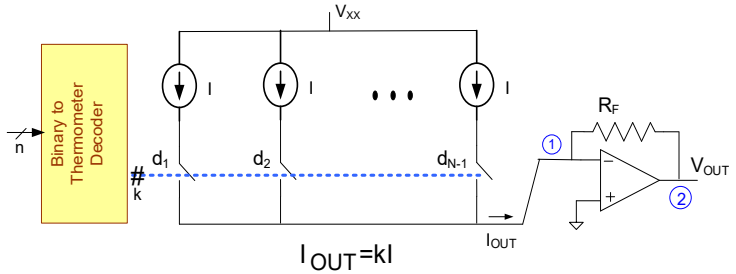
Switch impedance now of concern

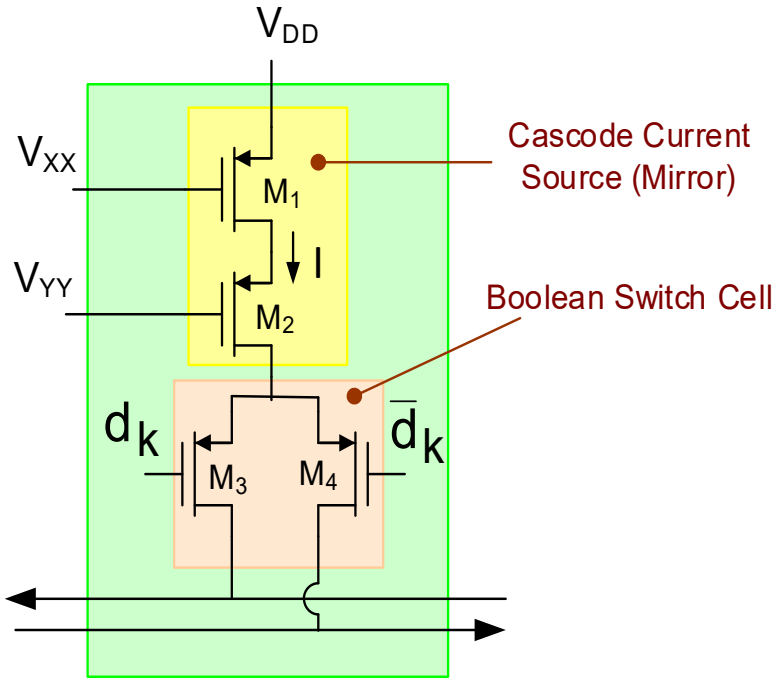
Output impedance of current sources now of concern

Current Steering DAC





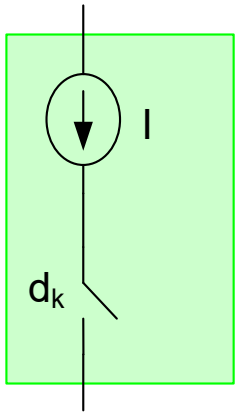


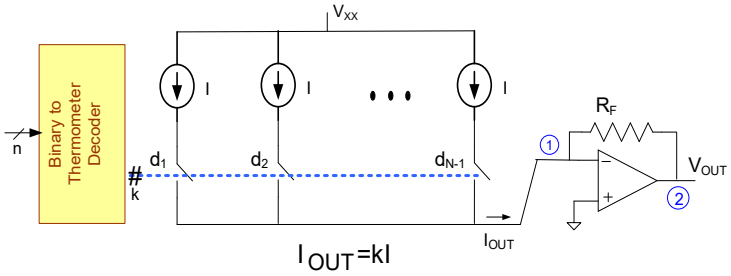


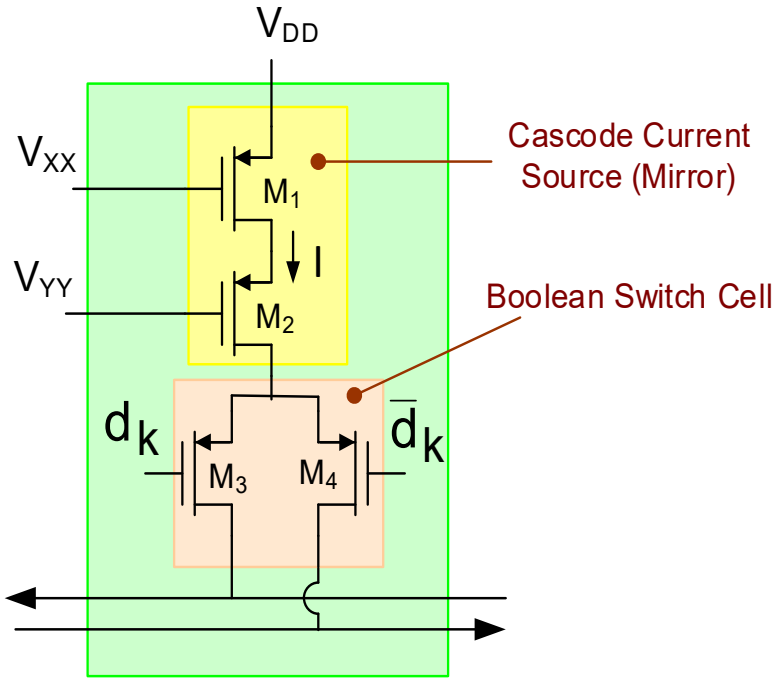
Cascoding reduces output conductance of current source

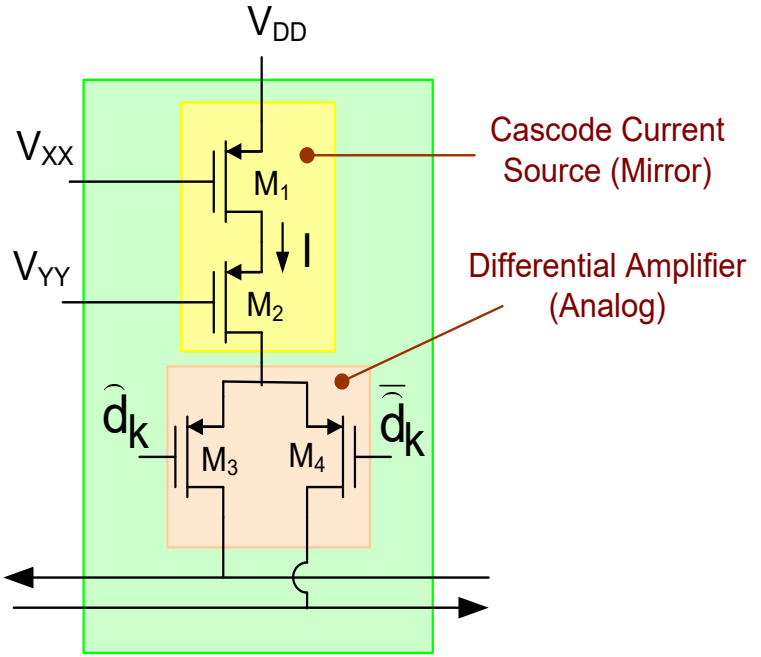
No power penalty, slight reduction in overhead

Current Steering DAC



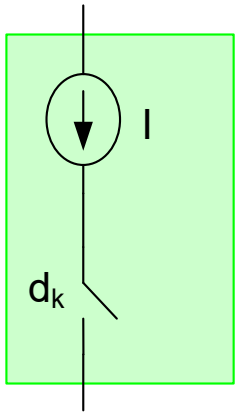


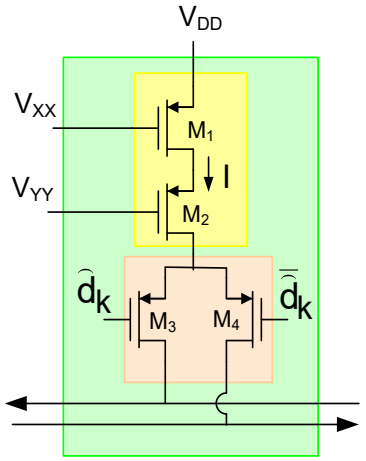


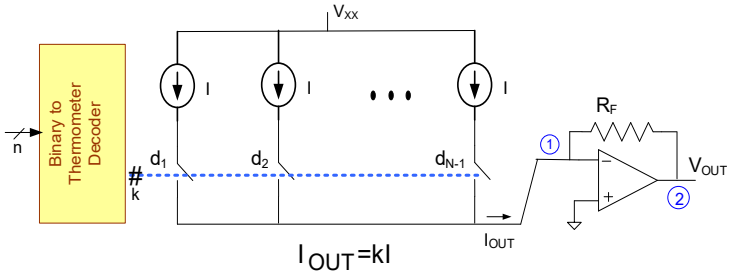


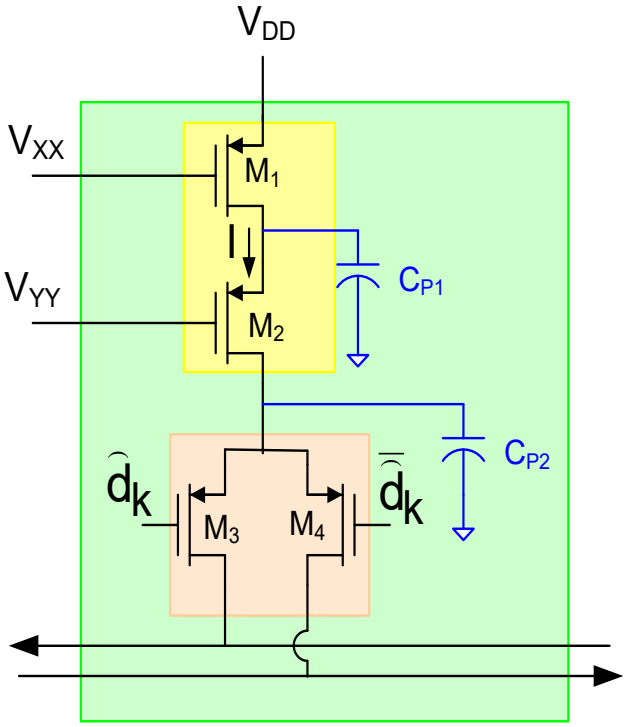
Steer rather than switch current
Reduced swing on control signals

Current Steering DAC

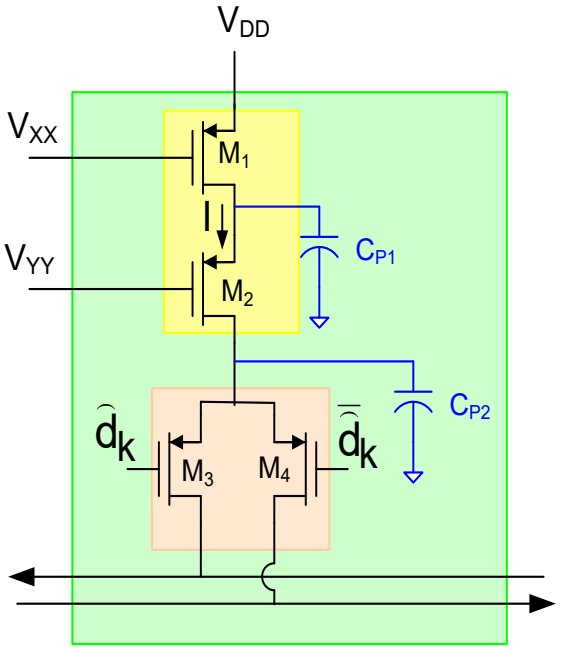


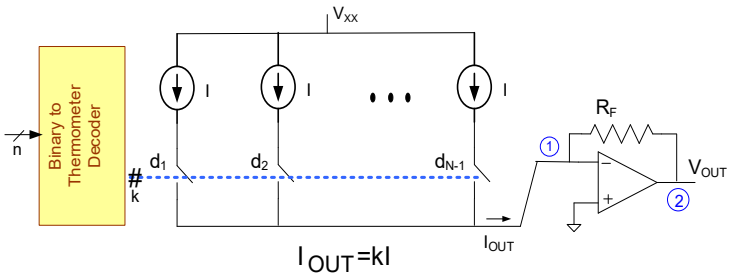


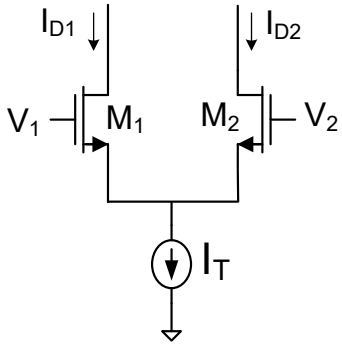


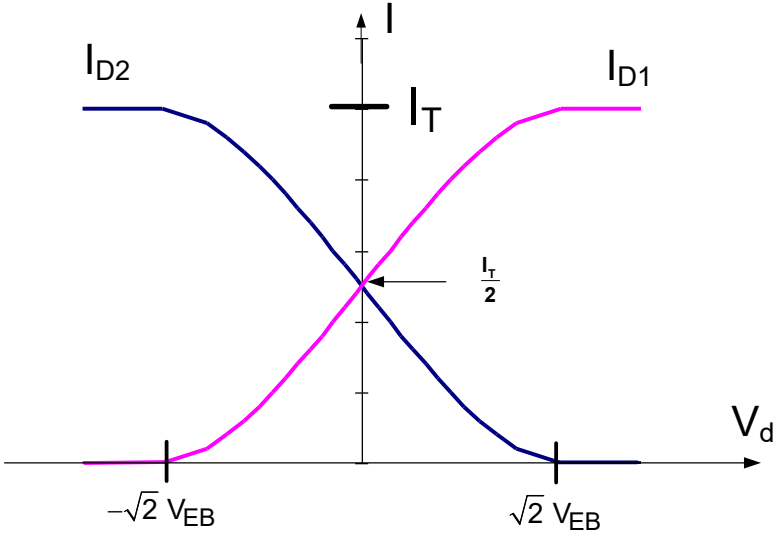


Current Steering DAC



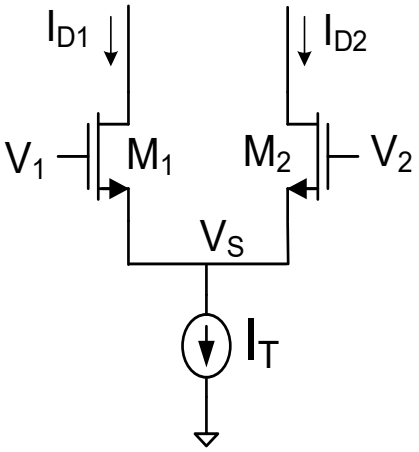


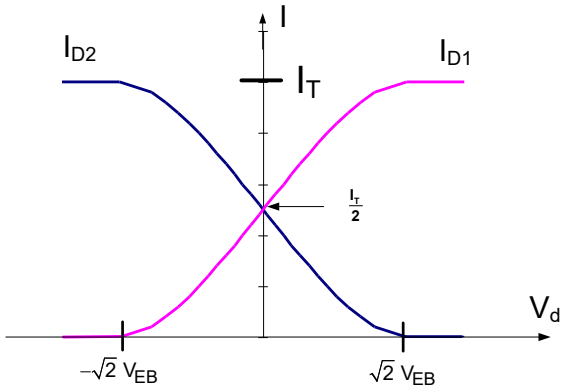




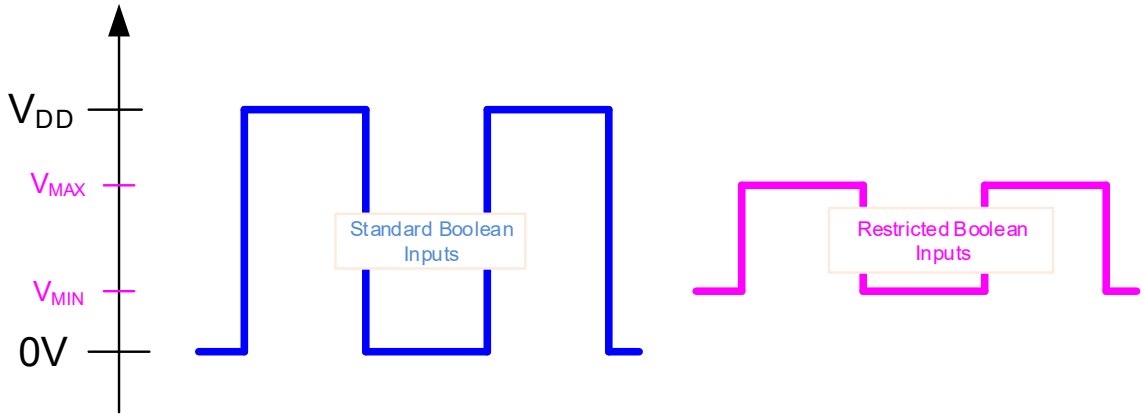
- Need only signal swing of $2\sqrt{2}V_{EB}$ to steer currents (so can reduce turn-on and turn-off times)
- Steering also results in cascoding with M_3 and M_4 thus increasing output impedance of current source (so can probably eliminate M_2)

Current Steering DAC

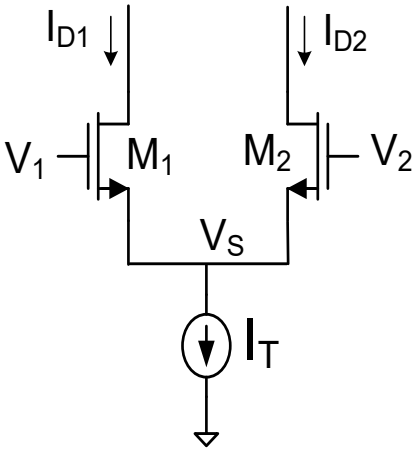


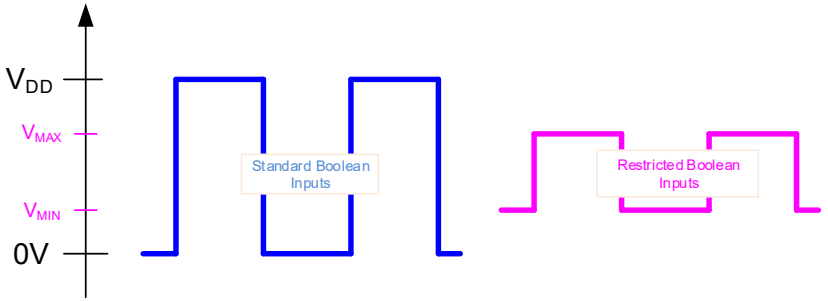


Reduced Signal Swing on V_S Node with Current Steering

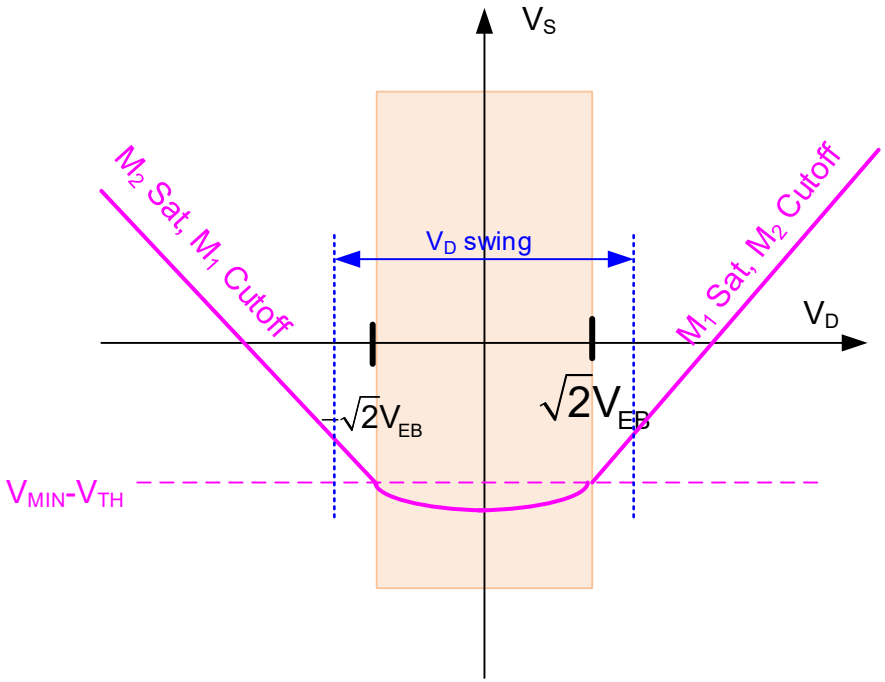


Current Steering DAC

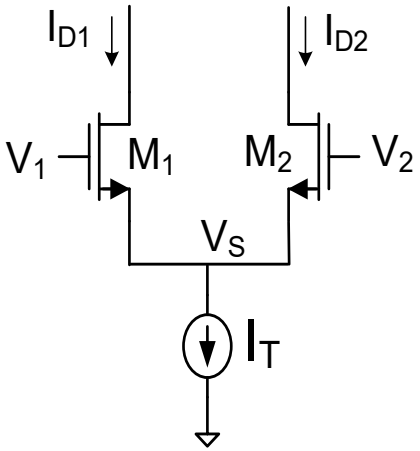


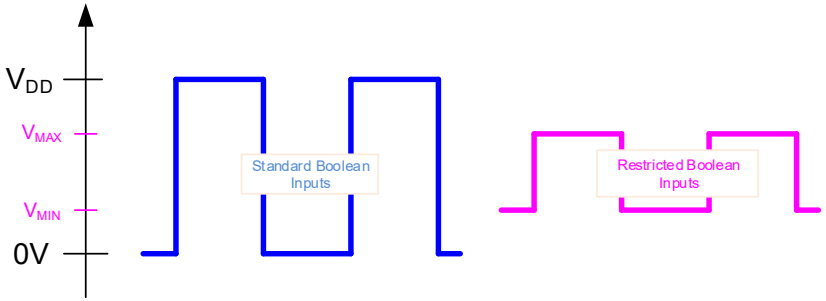


Reduced Signal Swing on V_S Node with Current Steering



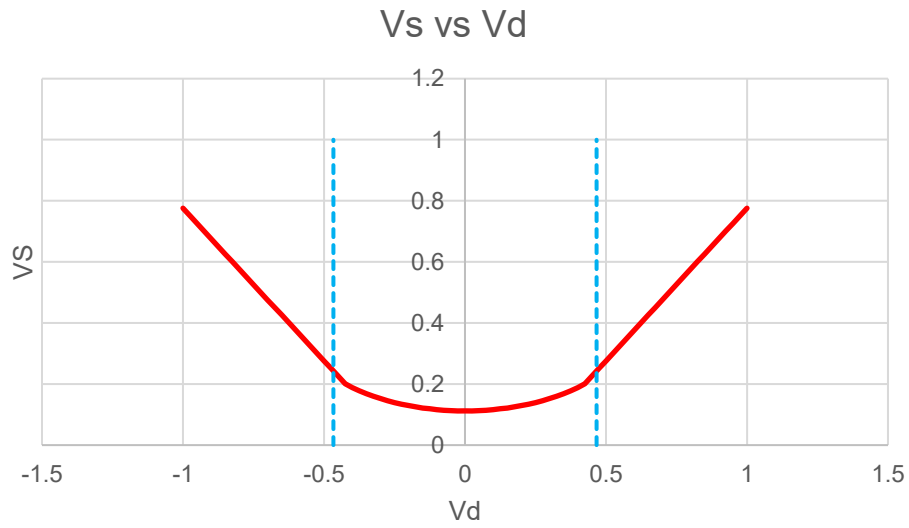
Current Steering DAC





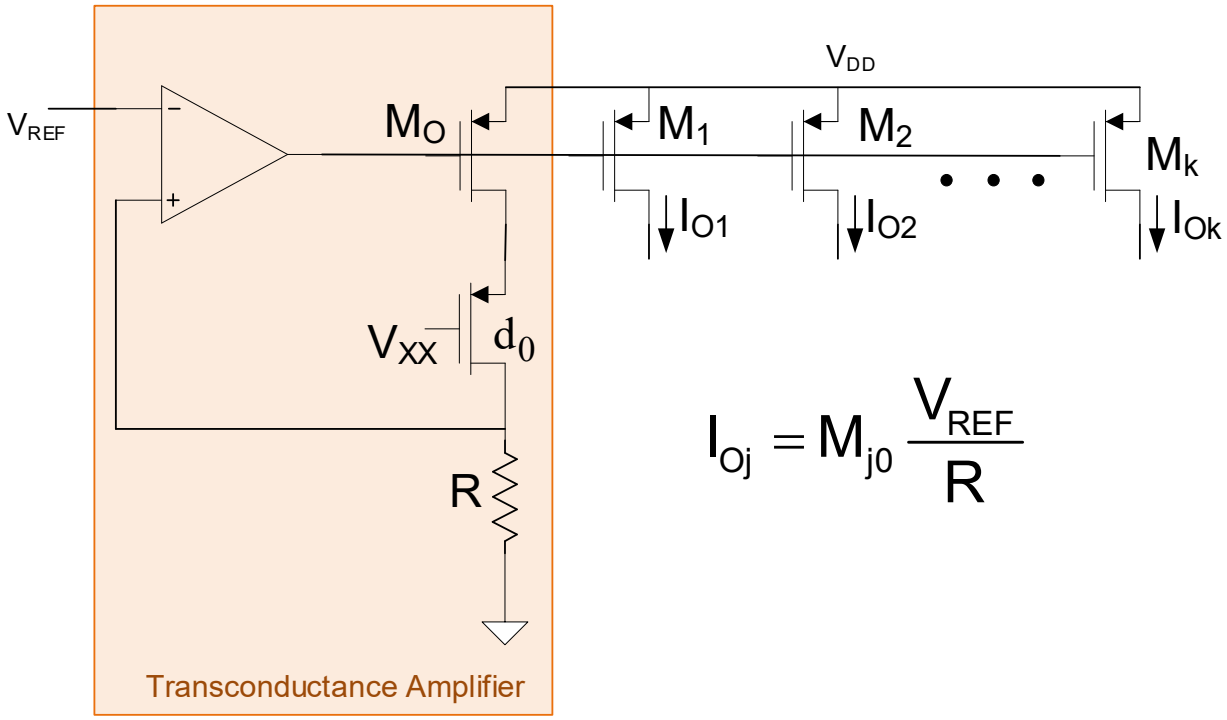
Reduced Signal Swing on V_S Node with Current Steering

Simulation Results: V_{TH}=0.4V, V_{MIN}=0.6V, V_{MAX}=1.07V,V_{EB}=0.3V,γ=1.1



V_S swing about 100mV

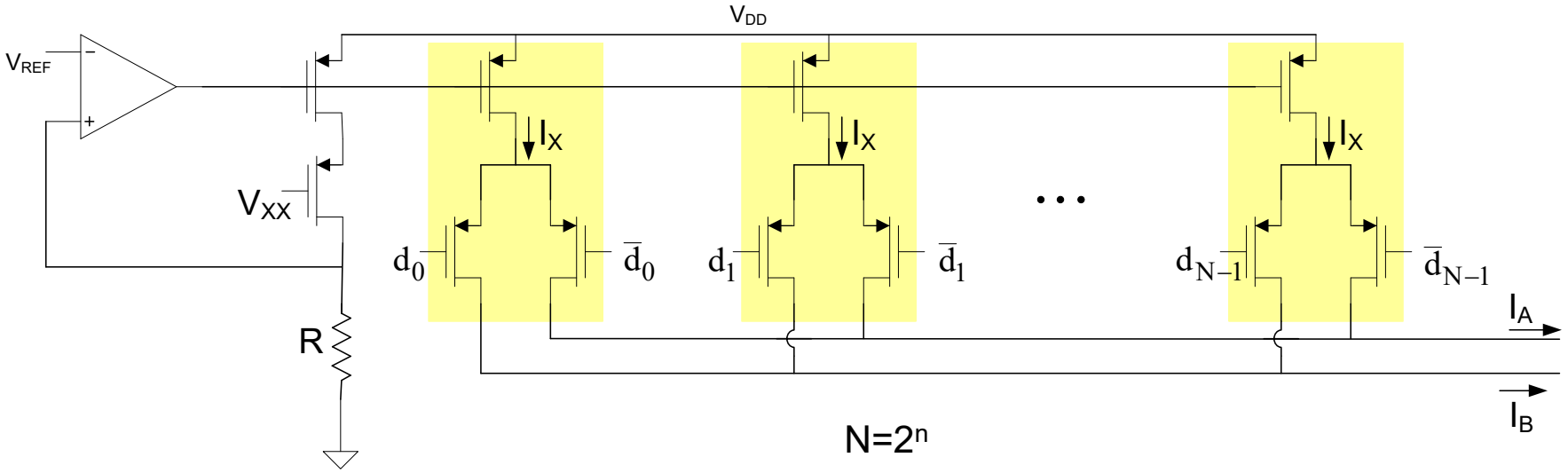
Multiple-output Transconductance Amplifier



$$I_{Oj} = M_{j0} \frac{V_{REF}}{R}$$

- Good linearity
- Each additional output requires only one additional transistor
- Relevant if MDAC output desired
- Cascoding of output devices useful if driving resistive load

Current Steering DAC with Supply Independent Biasing



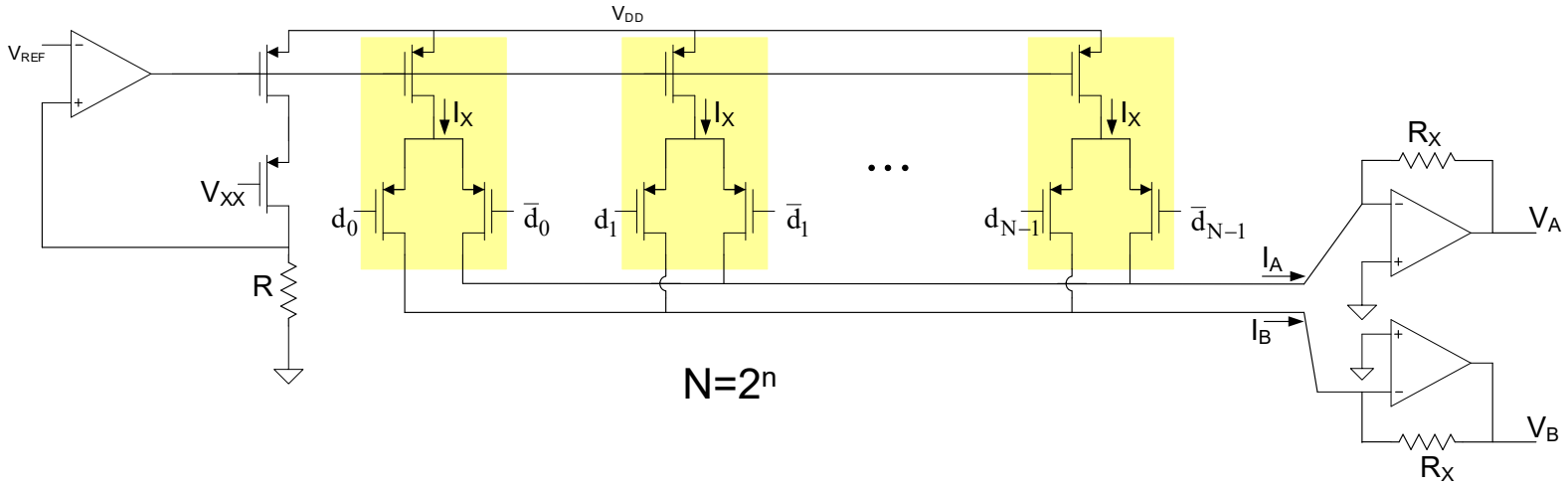
If transistors on top row are all matched, $I_X = V_{REF}/R$

Thermometer coded structure (requires binary to thermometer decoder)

$$I_A = \left(\frac{V_{REF}}{R}\right)\sum_{i=0}^{N-1} d_i$$

Provides Differential Output Currents

Current Steering DAC with Supply Independent Biasing

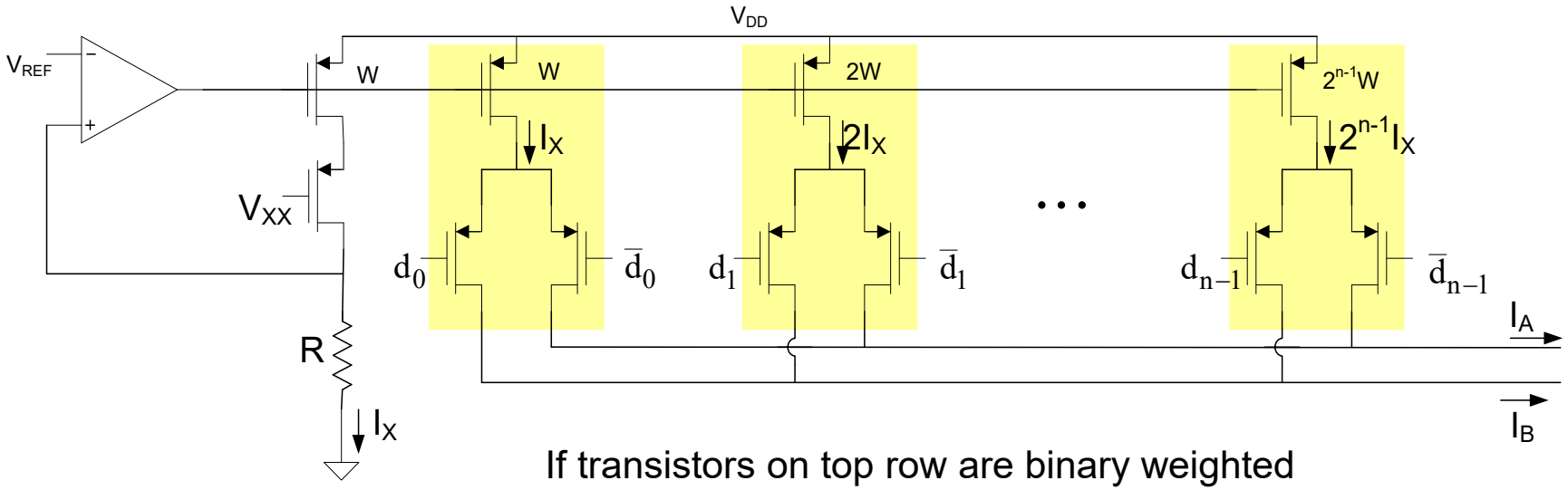


If transistors on top row are all matched, $I_X = V_{REF}/R$

$$V_A = \left(-V_{REF} \frac{R_A}{R} \right) \sum_{i=0}^{N-1} d_i$$

Provides Differential Output Voltages

Current Current Steering DAC with Supply Independent Biasing



If transistors on top row are binary weighted

$$I_A = \left(\frac{V_{REF}}{R}\right)\sum_{i=0}^{n-1} d_i 2^i$$

Provides Differential Output Currents

Usually use bundled unary cells
Can use current steering rather than current switching

(switched LSB:MSB notation)

Stay Safe and Stay Healthy !

End of Lecture 35